

Google Earth Engine Workshop

Gennadii Donchyts

Deltares

Resolutions

Temporal: months to seconds
Spatial: 1km to 1m
Spectral: 3-15 bands
Radiometric: 8 → 16bit

Coverage

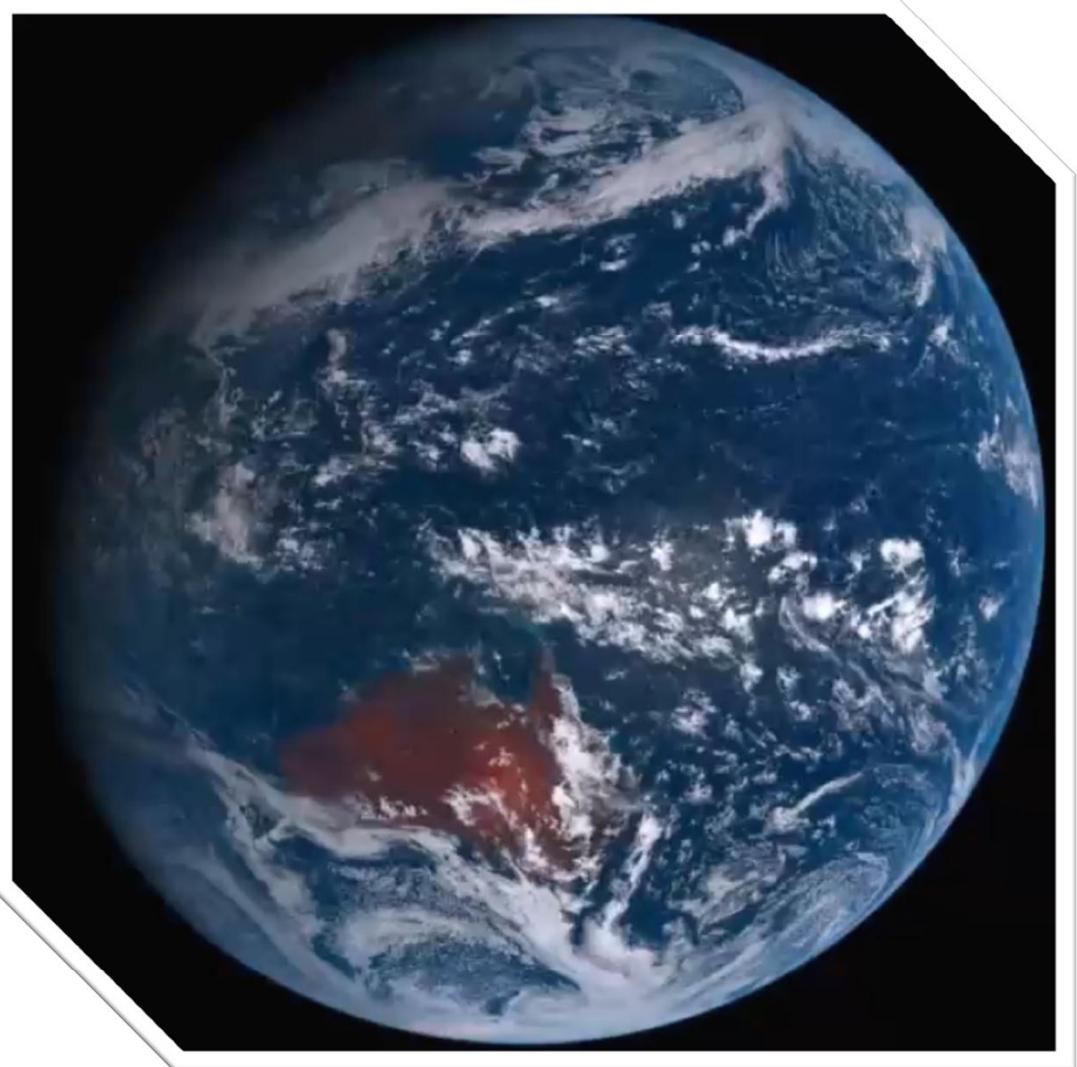
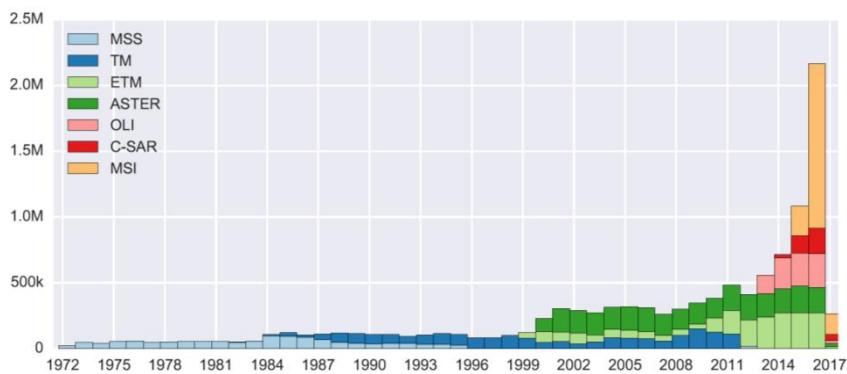
Local → Global

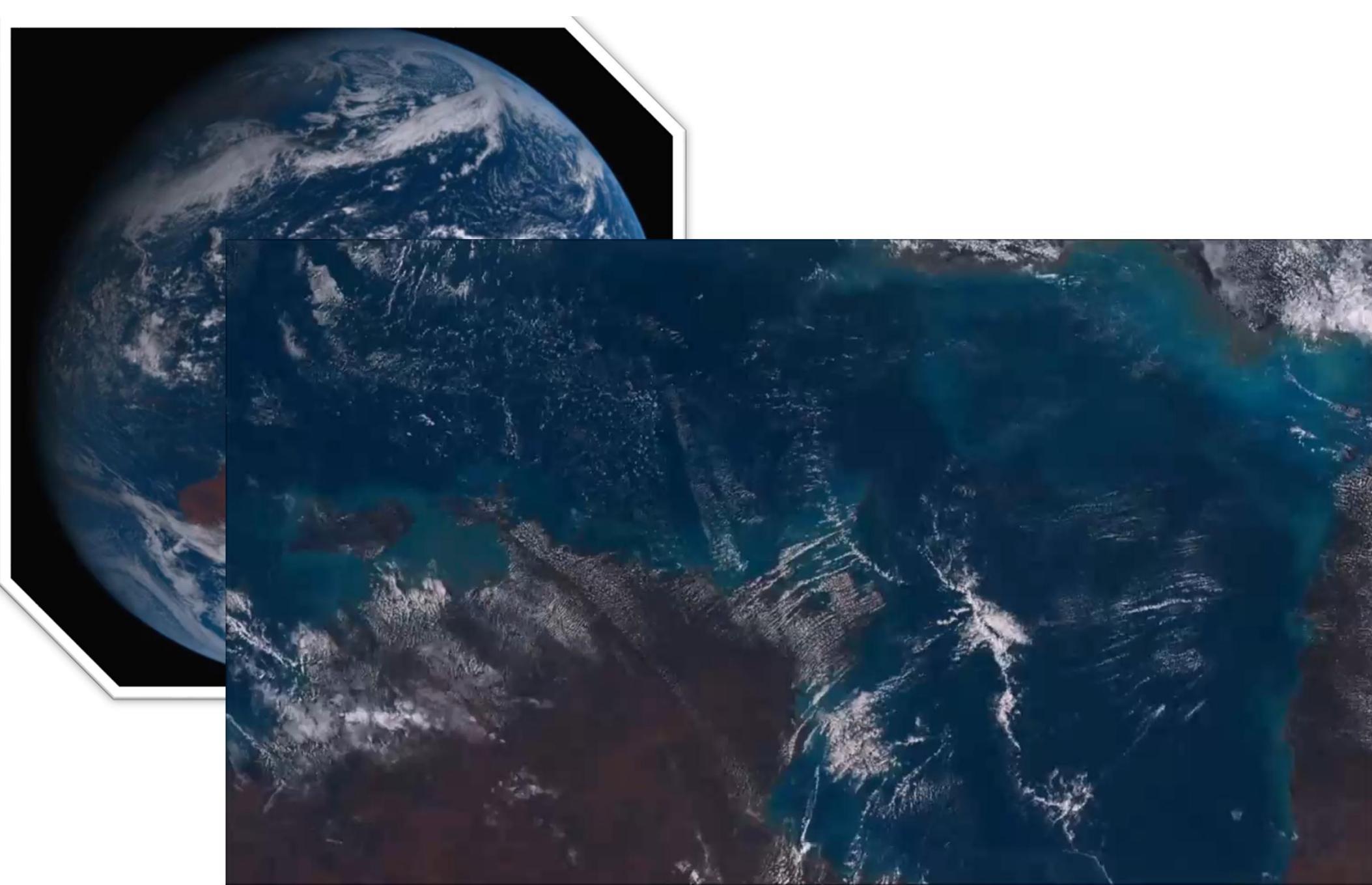
Volumes

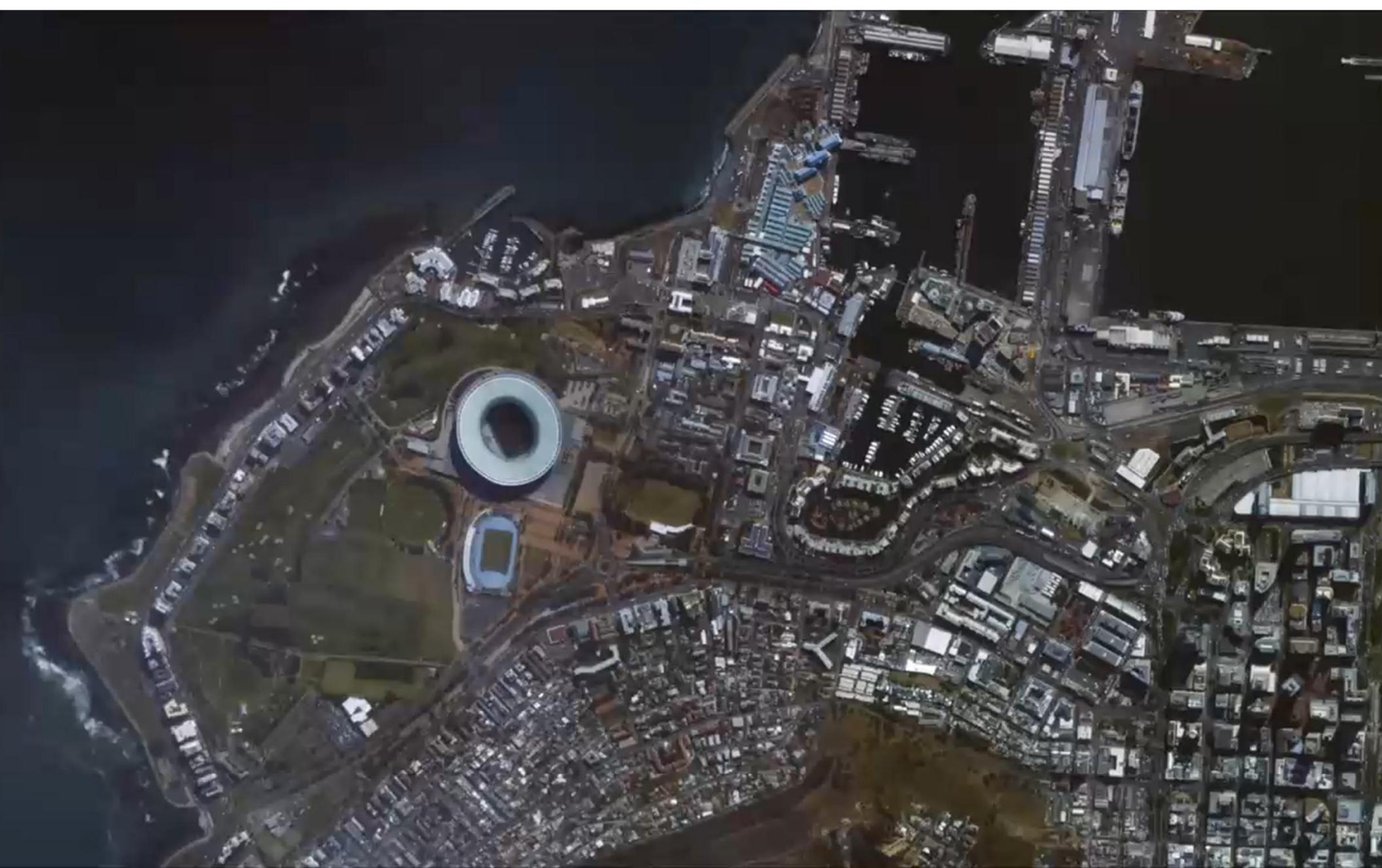
100 MB → 10 000 000 000 MB

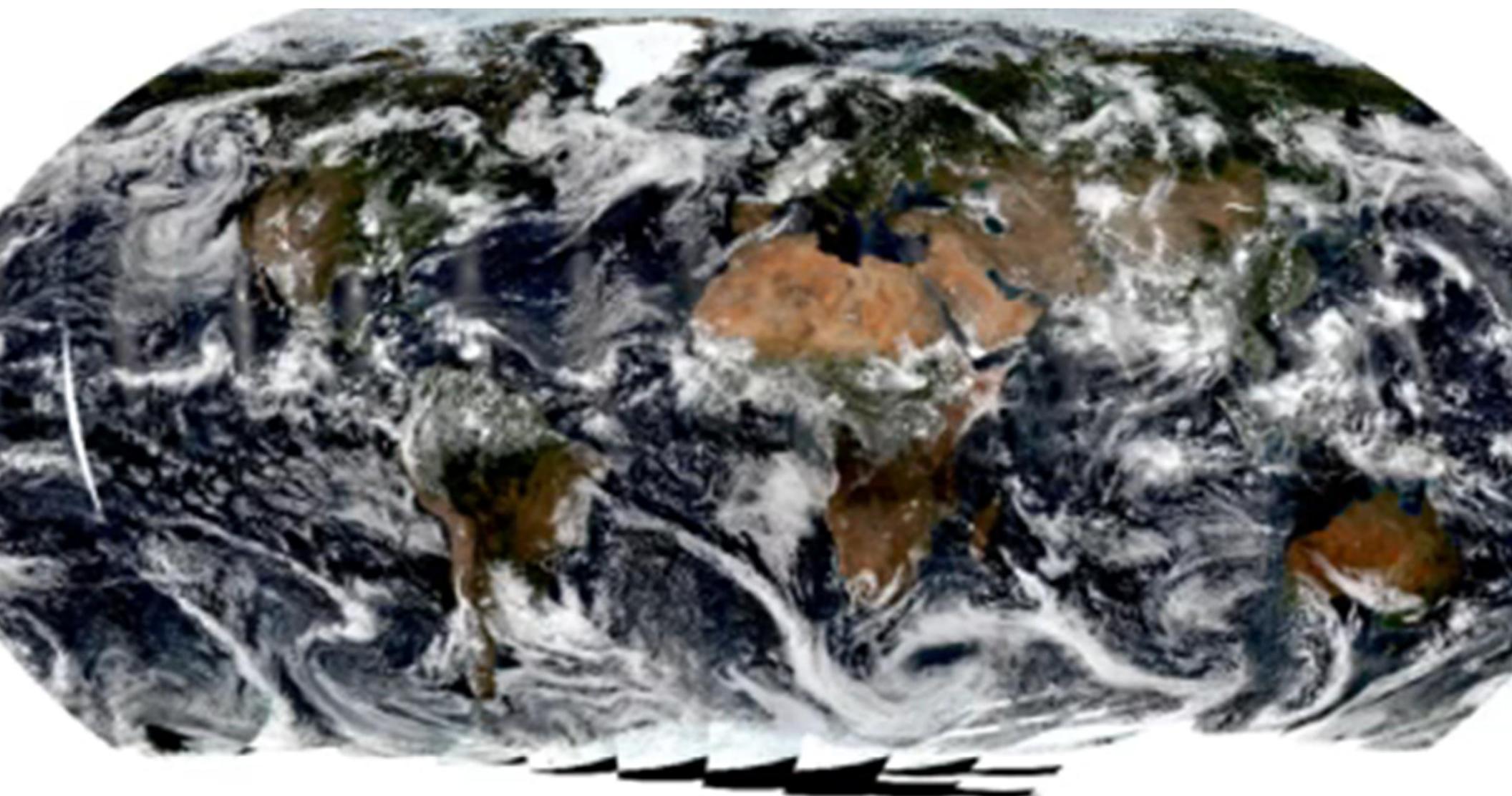
Availability

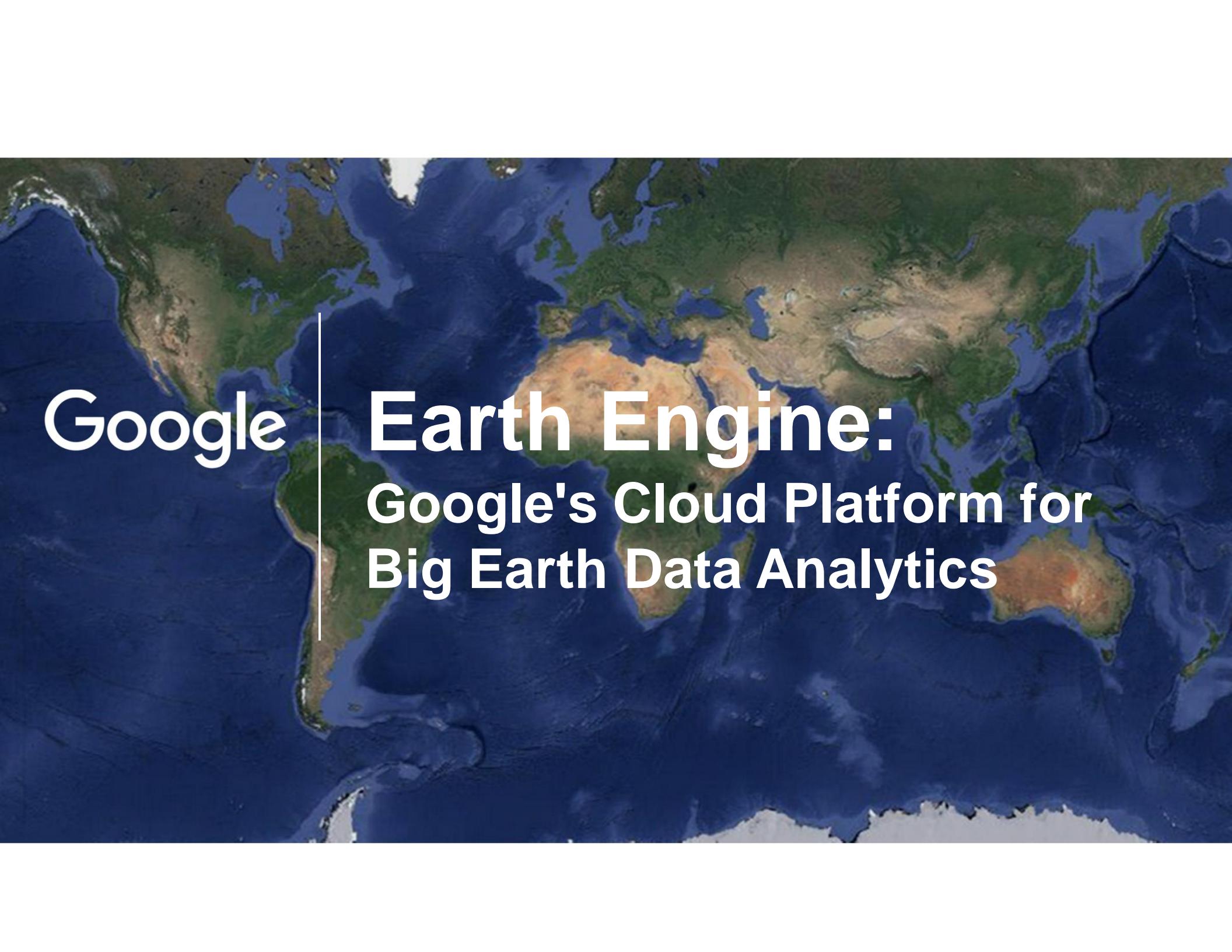
~2PB satellite images, <30m









The background of the slide is a satellite map of the Earth, showing the continents and oceans. The landmasses are depicted in various shades of green and brown, while the oceans are a deep blue. The map is centered on the Northern Hemisphere.

Google

Earth Engine:

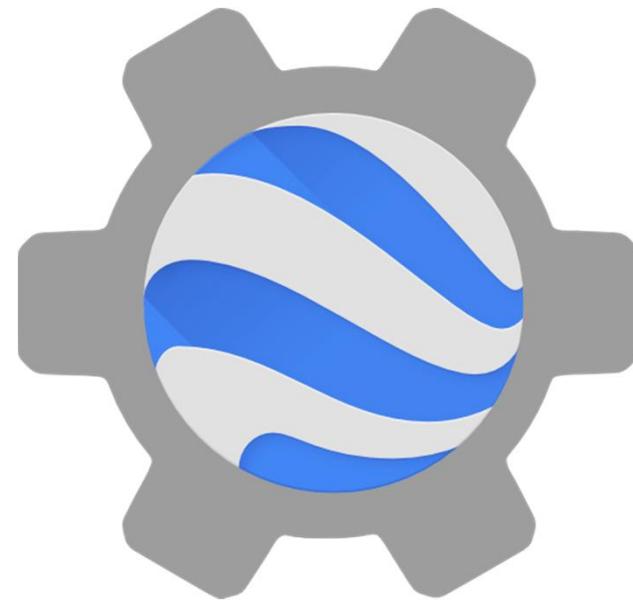
Google's Cloud Platform for Big Earth Data Analytics

Google Earth

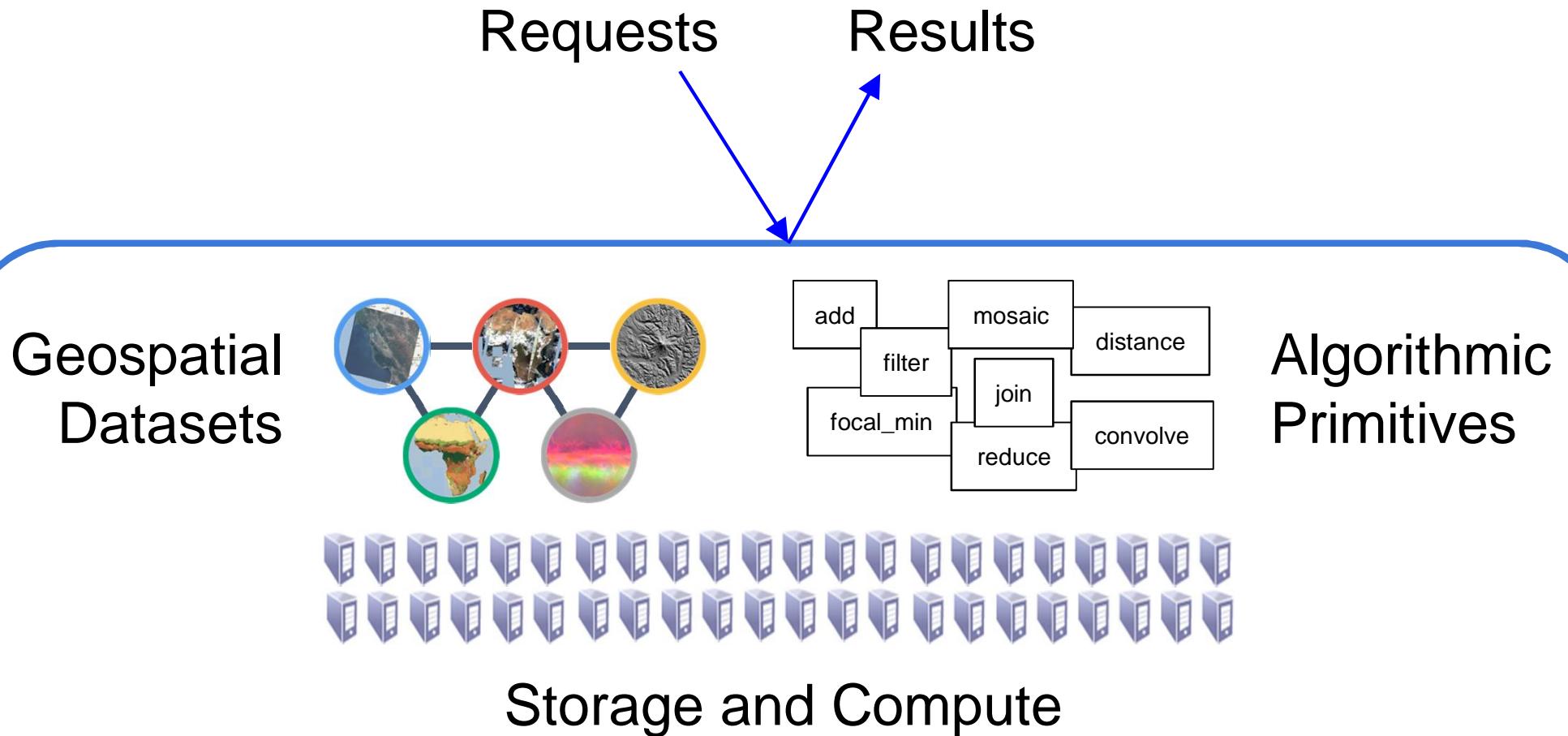


3-D Globe
Visualization

Earth Engine



Geospatial
Analysis



The Earth Engine Public Data Catalog



Landsat 4, 5, 7, 8
Raw, TOA, SR, ...



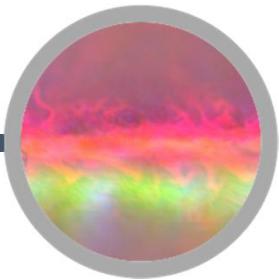
MODIS
Daily, NBAR, LST, ...



Terrain
SRTM, GTOPO, NED,
...



Land Cover
GlobCover, NLCD, ...



Atmospheric
NOAA NCEP, OMI, ...

... and many more, updating daily!

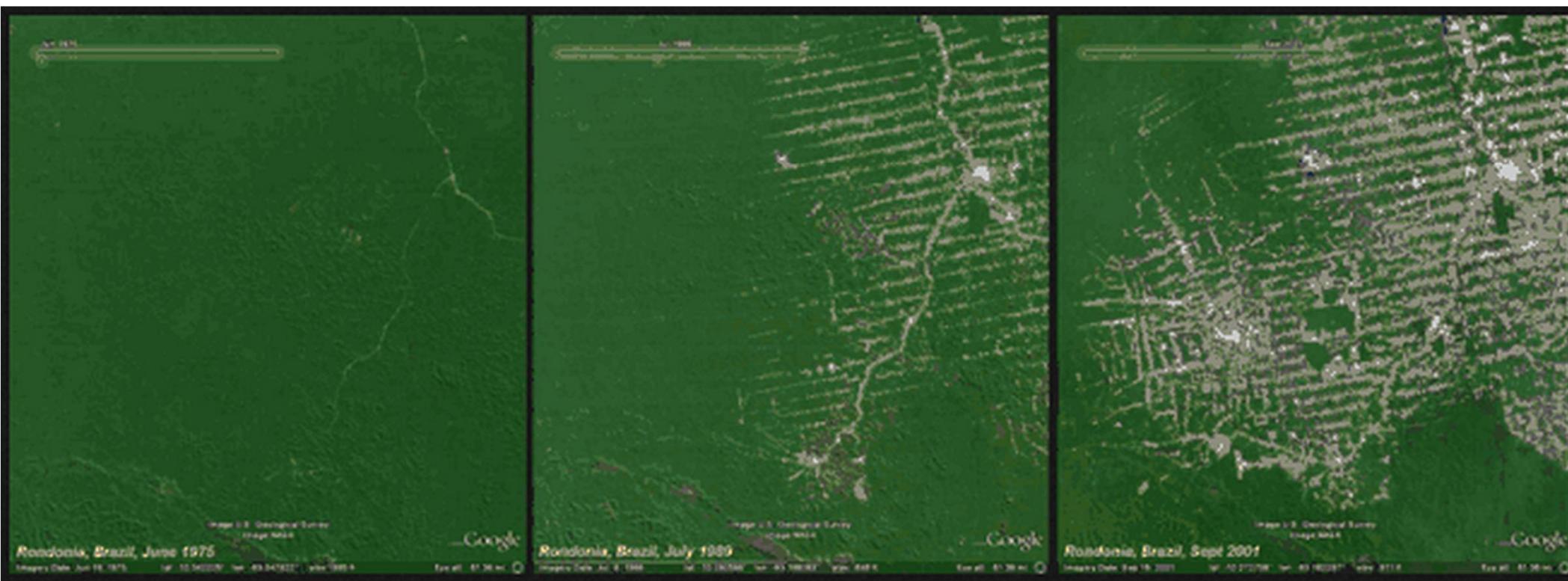
> 200 public datasets

> 5 million images

> 4000 new images every day

> 5 petabytes of data

Earth Engine: Origins



Global Forest Watch

GLOBAL
FOREST
WATCH
2.0

HOME

COUNTRIES

STORIES

MAP

BLOG

DATA

ABOUT

ENGLISH +

Find out what is happening
in forests right now

44,479
ALERTS IN THE PAST
YEAR

3
NEW FOREST
STORIES



Join the community



Analysis tool



Stay updated

JavaScript & Python API

```
// Make a median composite from two years of Landsat 7.  
// Load the image collection.  
var collection = ee.ImageCollection('LANDSAT/LE7_L1T');  
// Filter it down to 2011 and 2012.  
var filtered = collection.filterDate('2011-01-01', '2012-12-31');  
// For each pixel, for each band, calculate the median and make an image  
// of the result. The median tends to remove clouds, shadows, data gaps.  
var medianImage = filtered.median();  
// Add the image to a map.  
Map.addLayer(medianImage, {bands:['B3', 'B2', 'B1'], min:35, max:170});
```

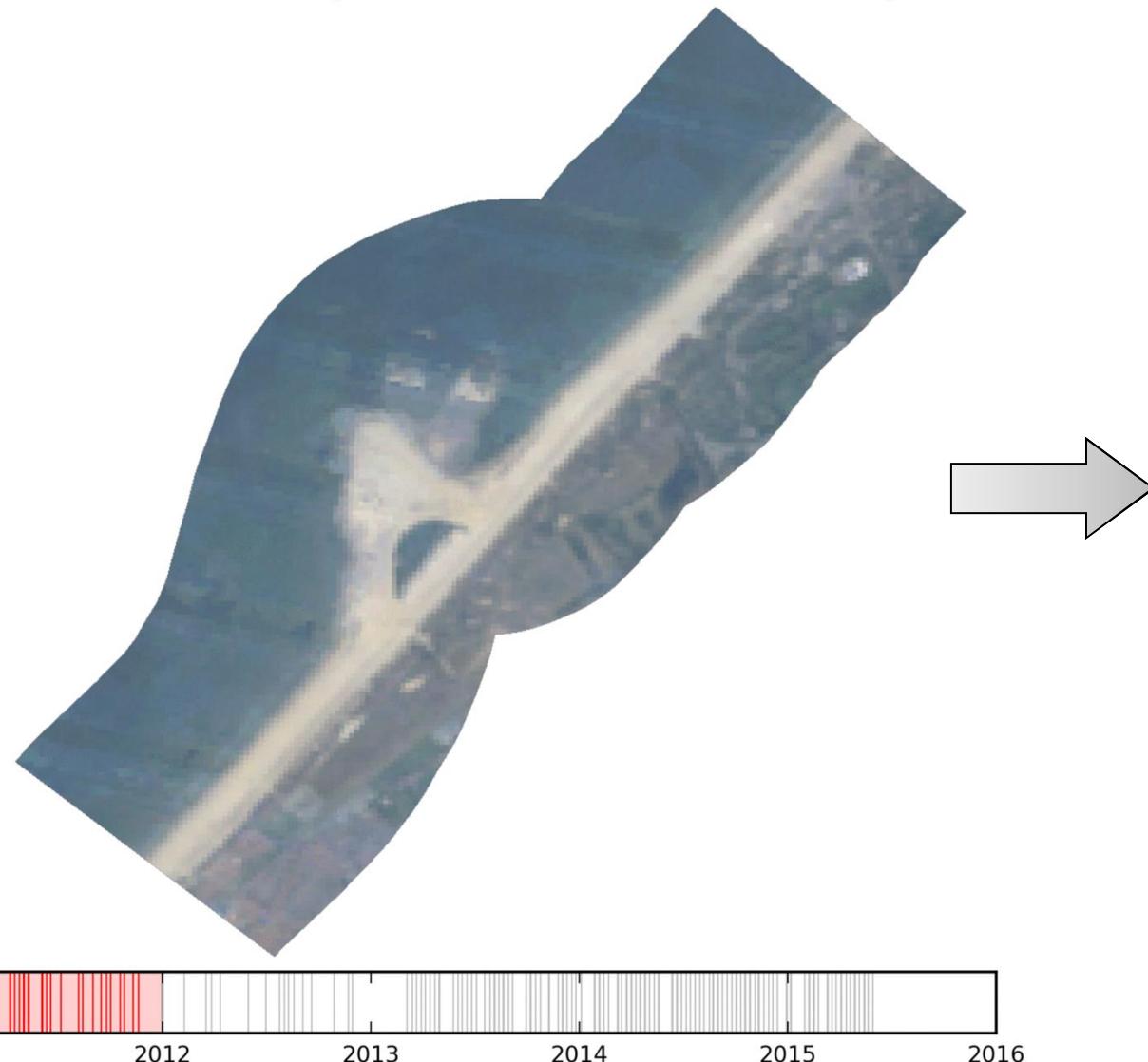
Code Editor link:

<https://code.earthengine.google.com/d7e0877fe7ad644bd6b50e6843150469>

Coastline Extraction – Zandmotor



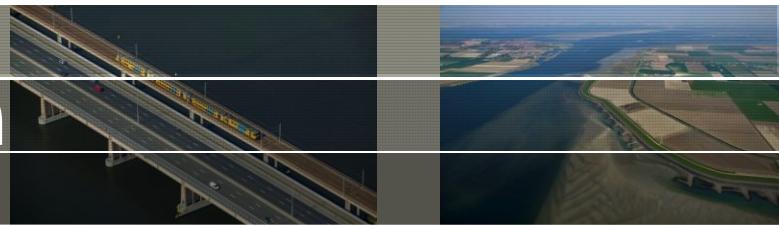
Zandmotor [2011/01/01 to 2012/01/01]



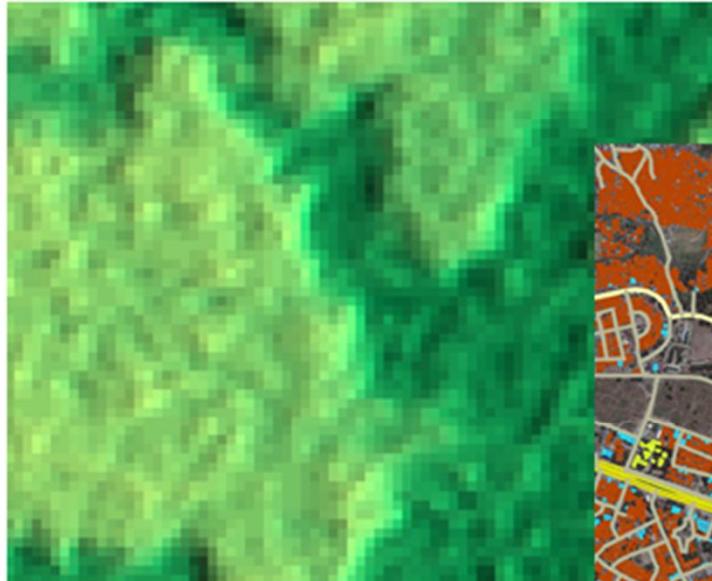
- 2011/01/01 to 2012/01/01
- 2012/01/01 to 2012/12/31
- 2012/12/31 to 2013/12/31
- 2013/12/31 to 2014/12/31
- 2014/12/31 to 2015/12/31



Participatory DEM generation



SRTM 30m



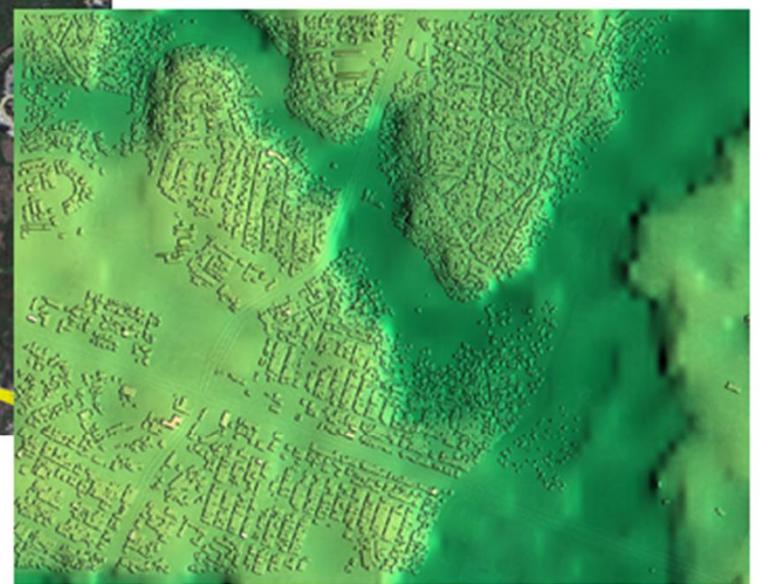
OSM data



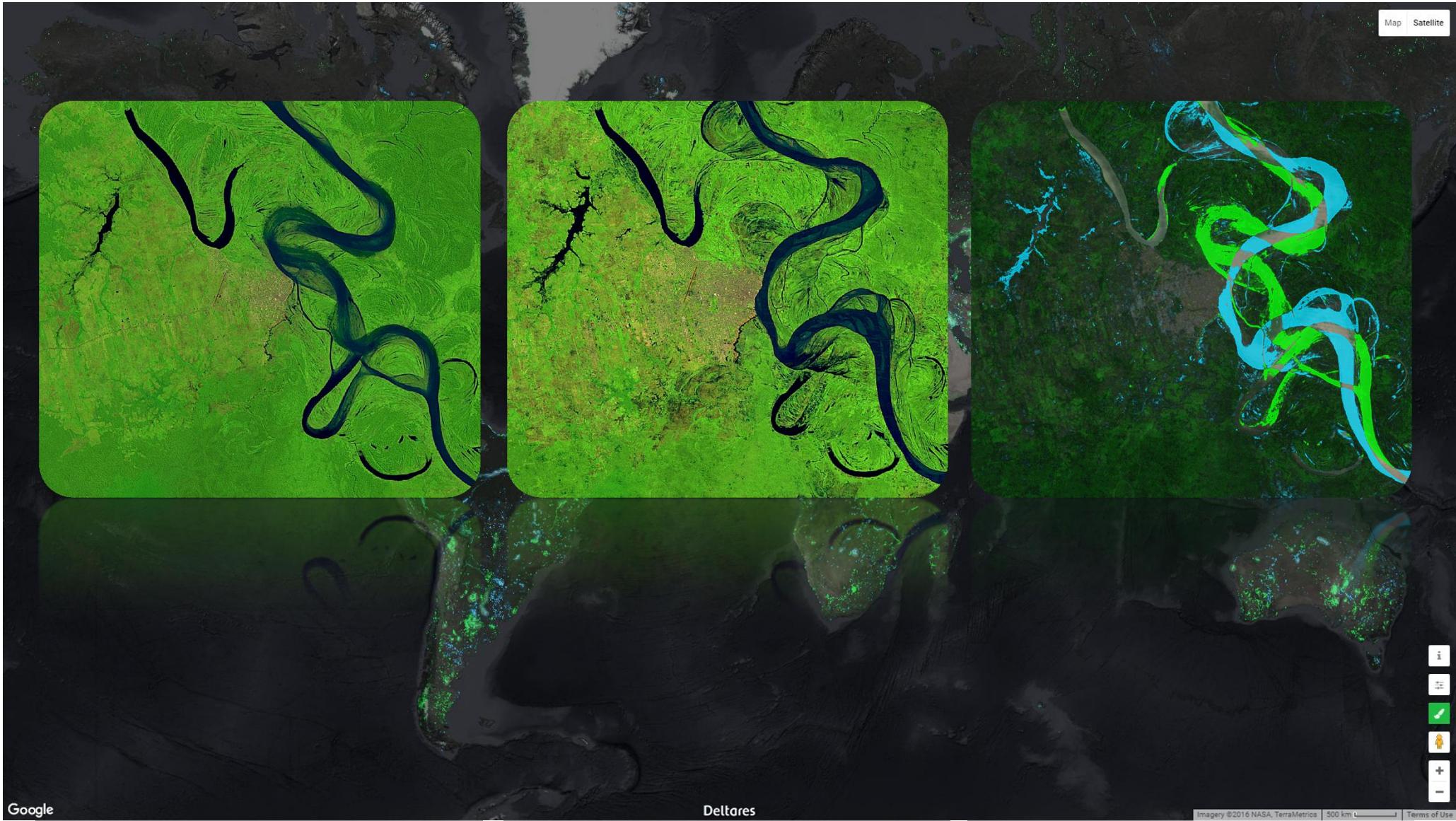
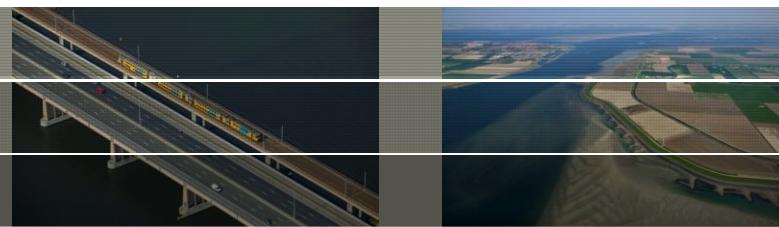
SRTM + OSM fusion

=

HighRes Digital Surface Model



Aqua Monitor



Google

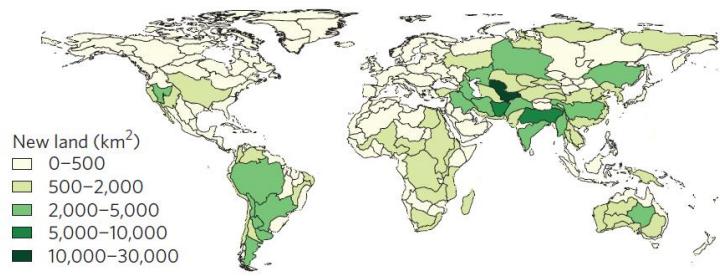
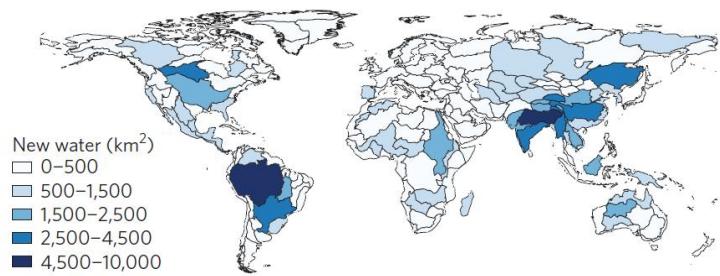
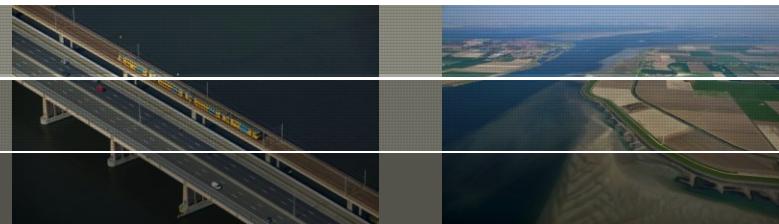
Deltas

Imagery ©2016 NASA, TerraMetrics | 500 km | Terms of Use

<http://aqua-monitor.appspot.com>

Deltas

Aqua Monitor



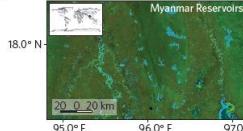
Name	Area (km^2)
Tibetan Plateau	7,661
Amazon River	7,058
Ganges-Brahmaputra Rivers	5,495
Rio de la Plata	4,410
River Nelson	4,101
India	3,677
River Amur	3,494
Yangtze River	3,238
Tigris and Euphrates Rivers	2,636
Thanlyin; Sittang; Ayeyarwady	2,592
Indus River	2,312
Mississippi River	2,231
Mekong River	2,074

Name	Area (km^2)
Aral Sea	27,841
Meghna River	9,580
Hamun Lake	6,044
Tigris and Euphrates Rivers	4,897
Amazon River	4,888
Lake Eyre	4,672
Rio de la Plata	4,020
India	3,851
Lake Urmia, Caspian Sea	3,759
Great Salt Lake; Malheur Lake	3,752
Ural River	3,455
Amur River	3,344
Ob River	3,068

Name	Area (km^2)
Myanmar Reservoirs	7,661
Hwanggang Dam, North Korea	7,058
Dubai	5,495
Singapore	4,410
Ganges-Brahmaputra Delta, South Asia	4,101
Taiji Naier Lakes, China	3,677
Aral Sea	3,494
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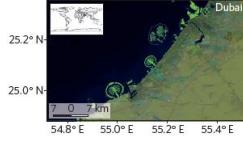
a



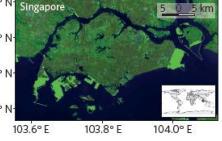
b



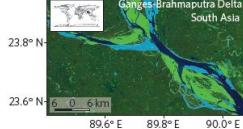
c



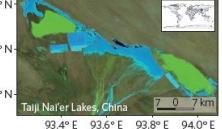
d



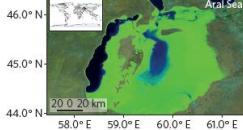
e



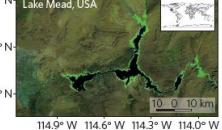
f



g



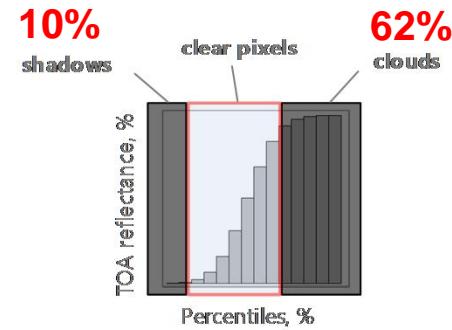
h



Deltares

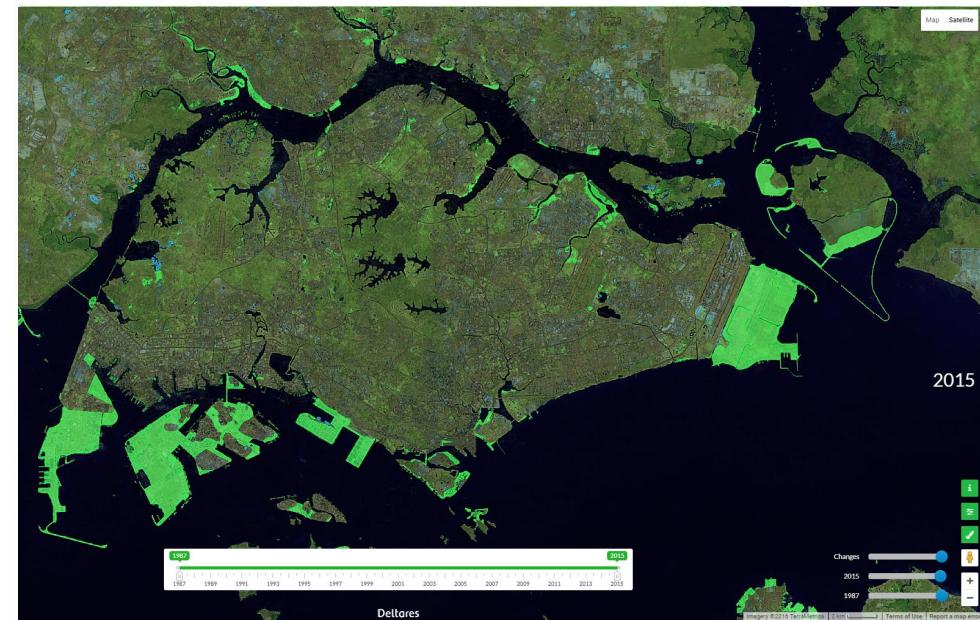
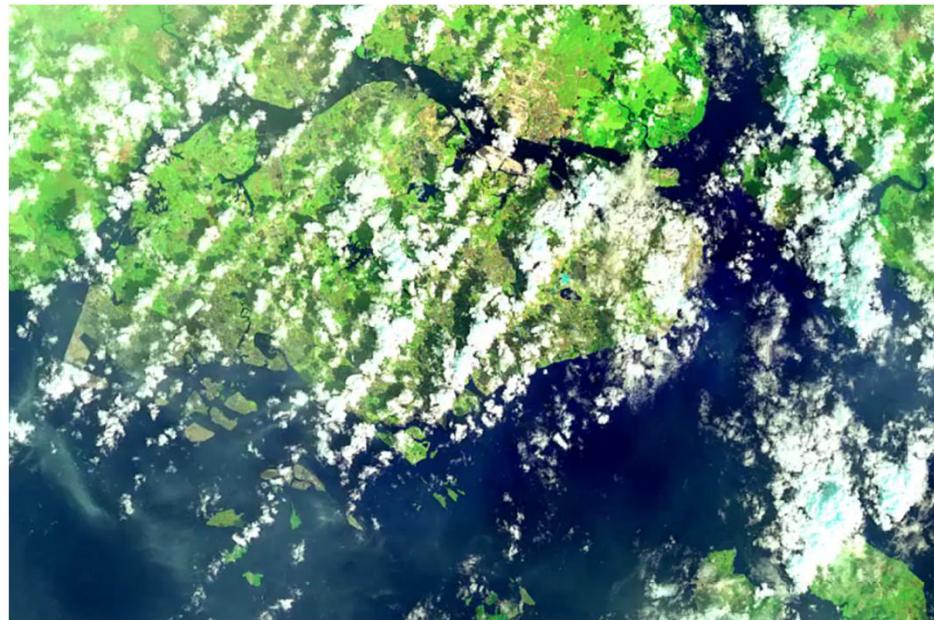


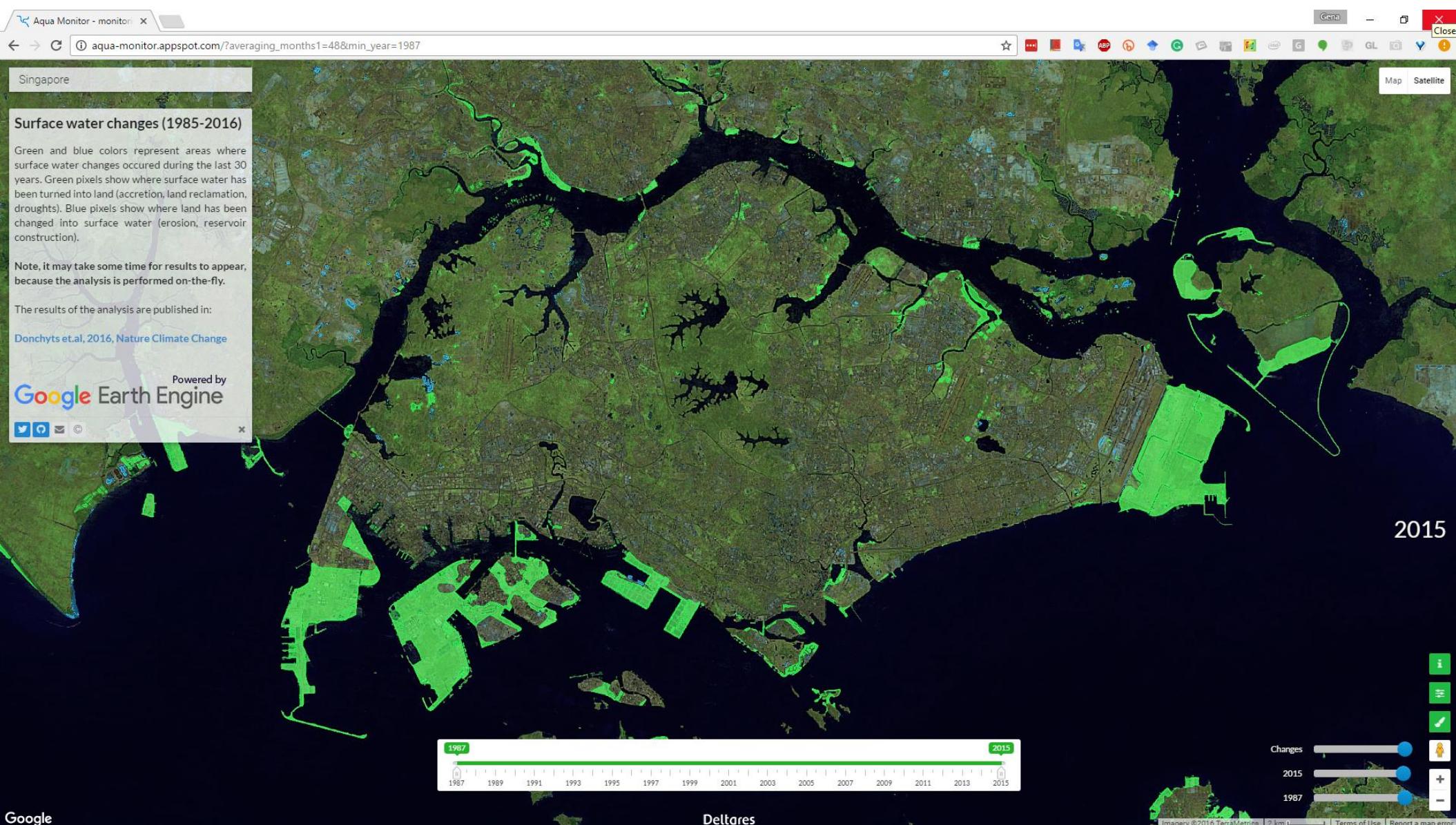
$$F(\rho) = \int_{-\infty}^{\rho^i} P(\rho) d\rho$$

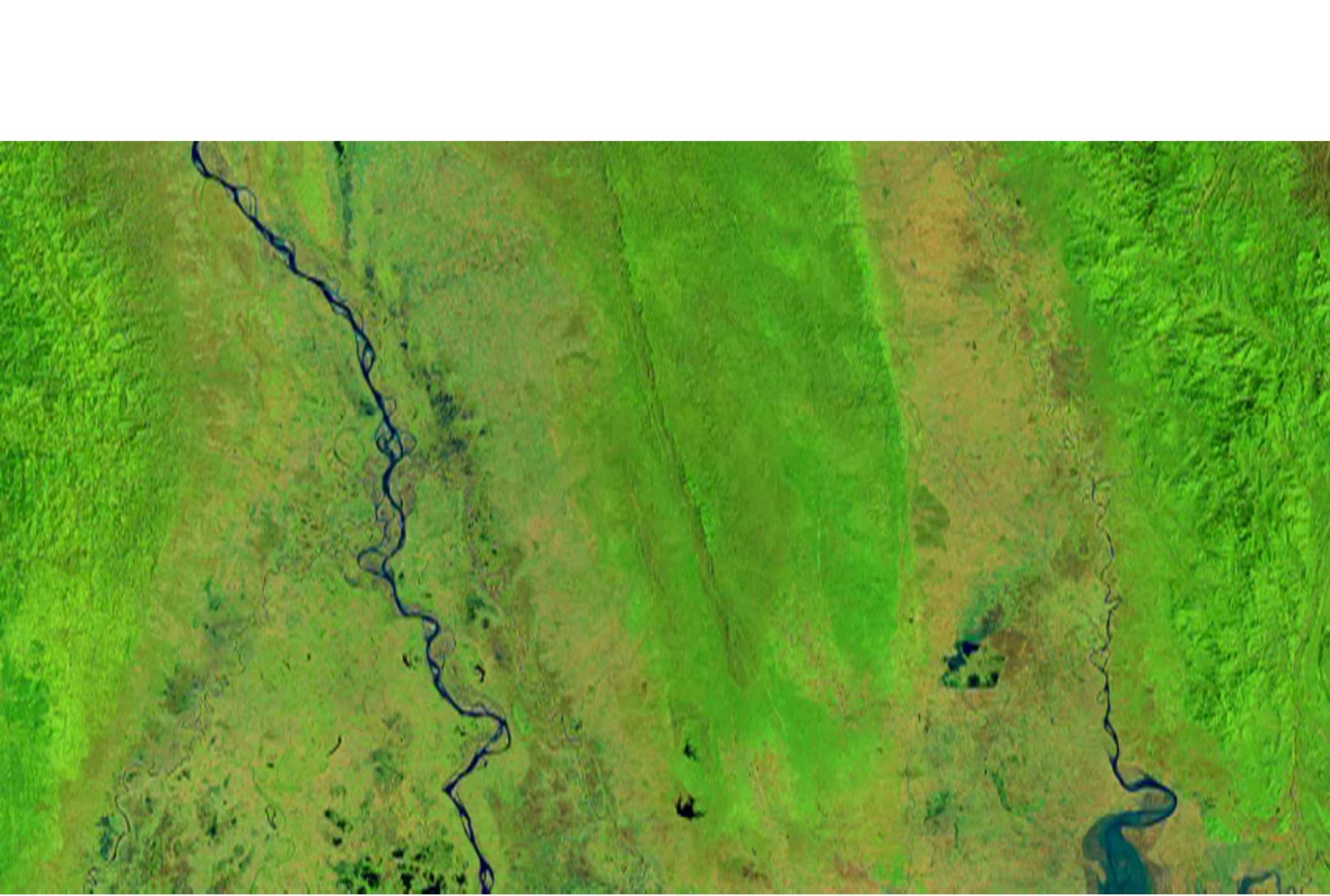


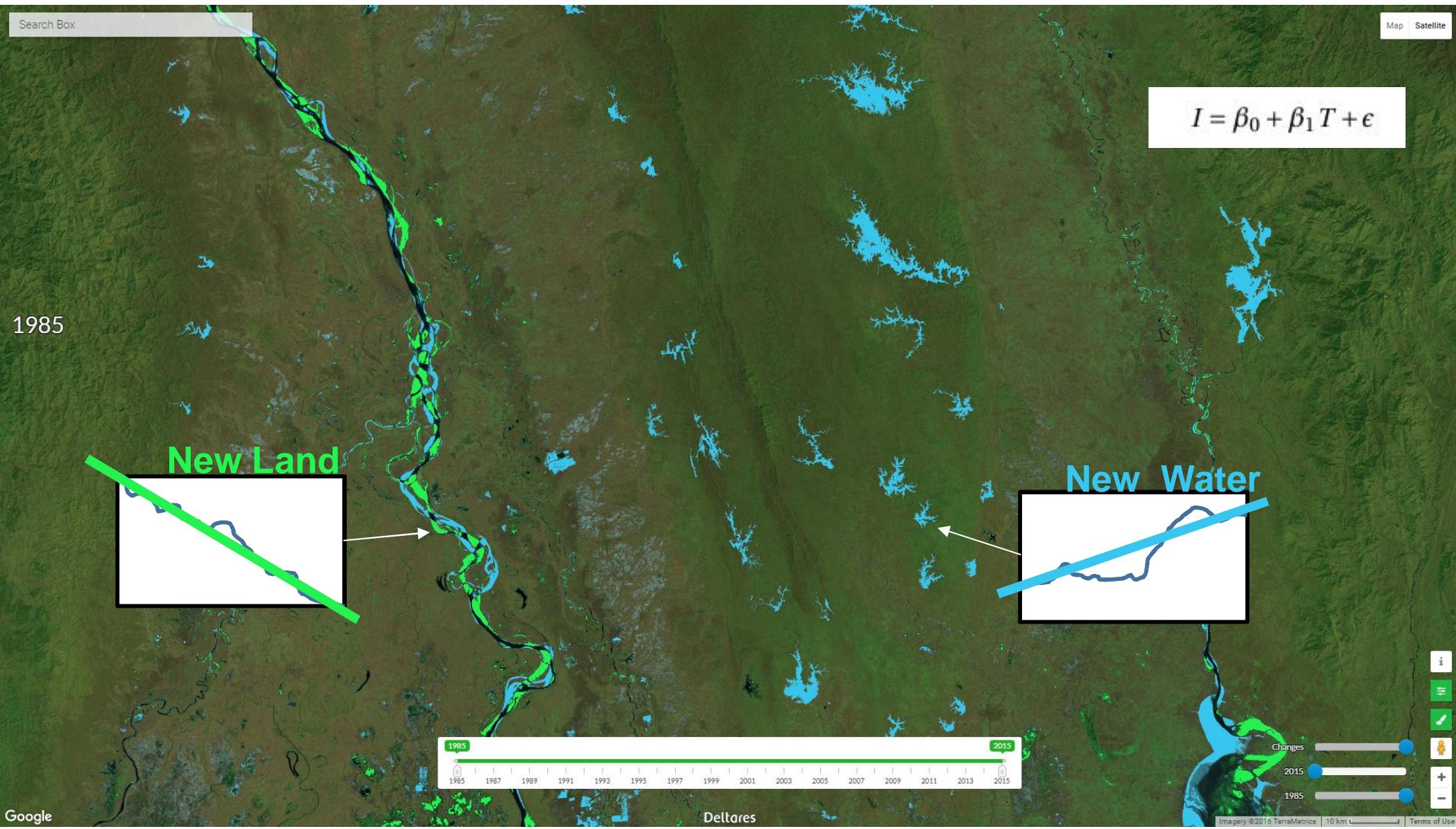
$$I = \frac{\rho_{green}^i - \rho_{nir}^i}{\rho_{green}^i + \rho_{nir}^i}$$

$$I = \beta_0 + \beta_1 T + \epsilon$$



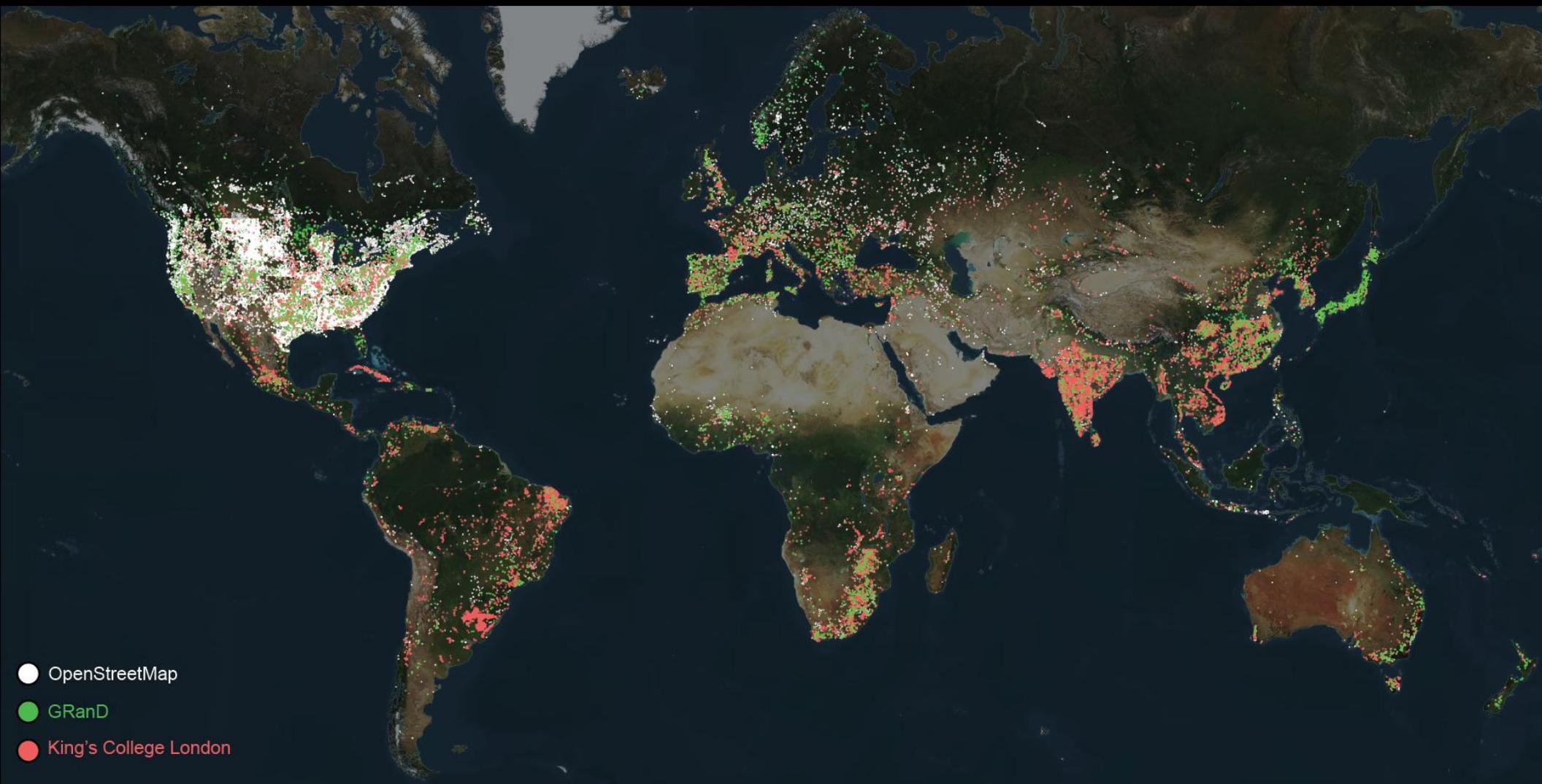






<http://aqua-monitor.appspot.com>

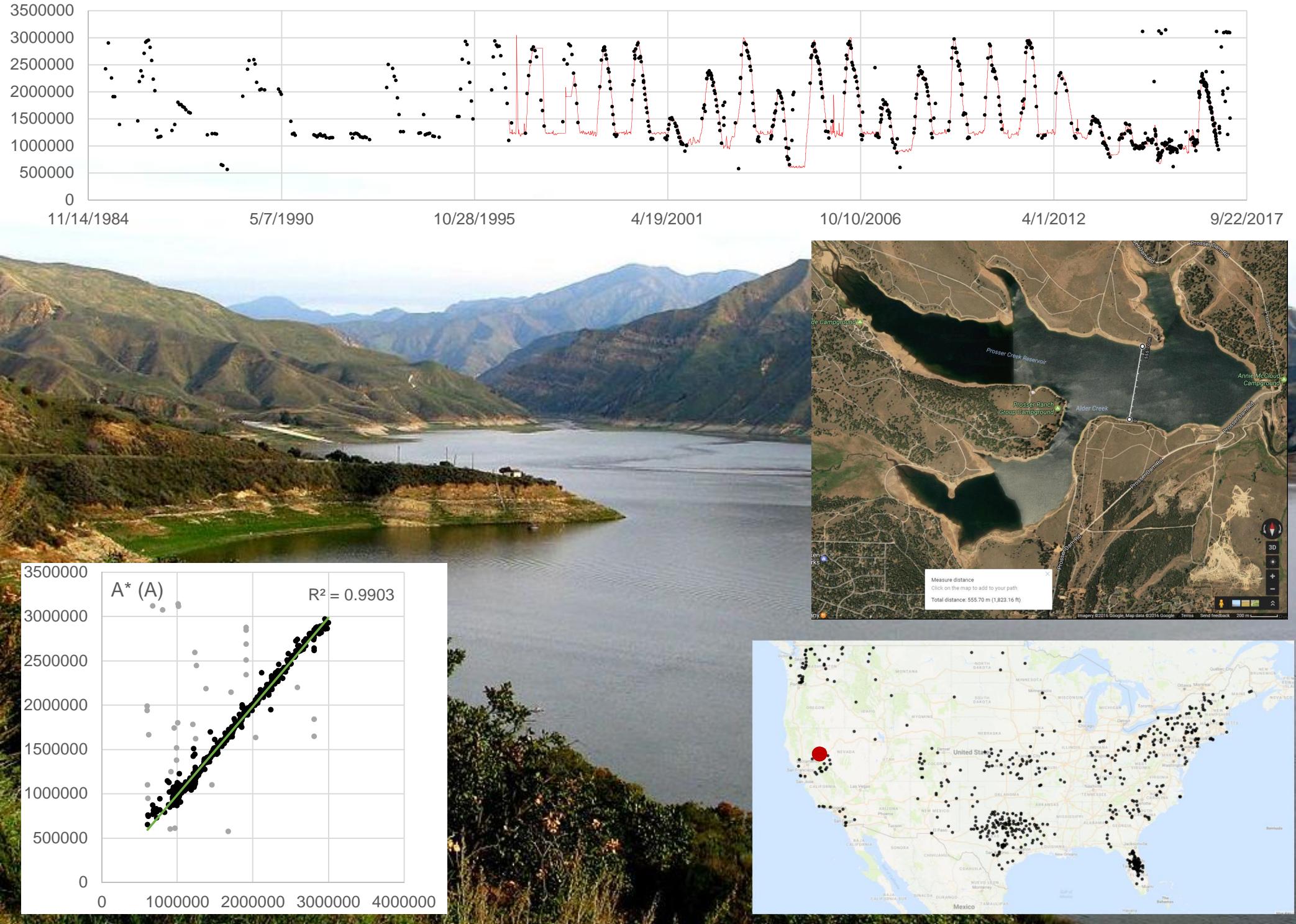
About 150 000 reservoirs mapped today (GRanD \approx 6000)



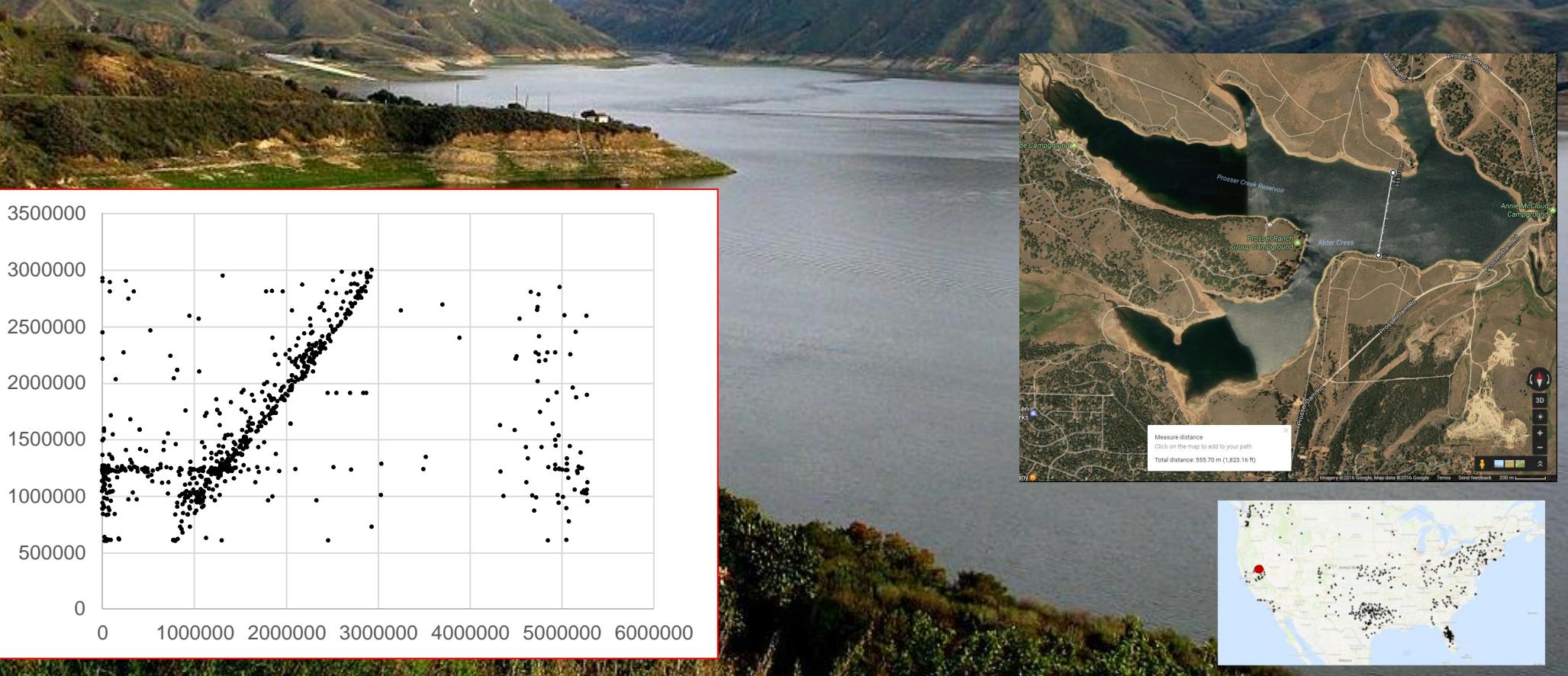
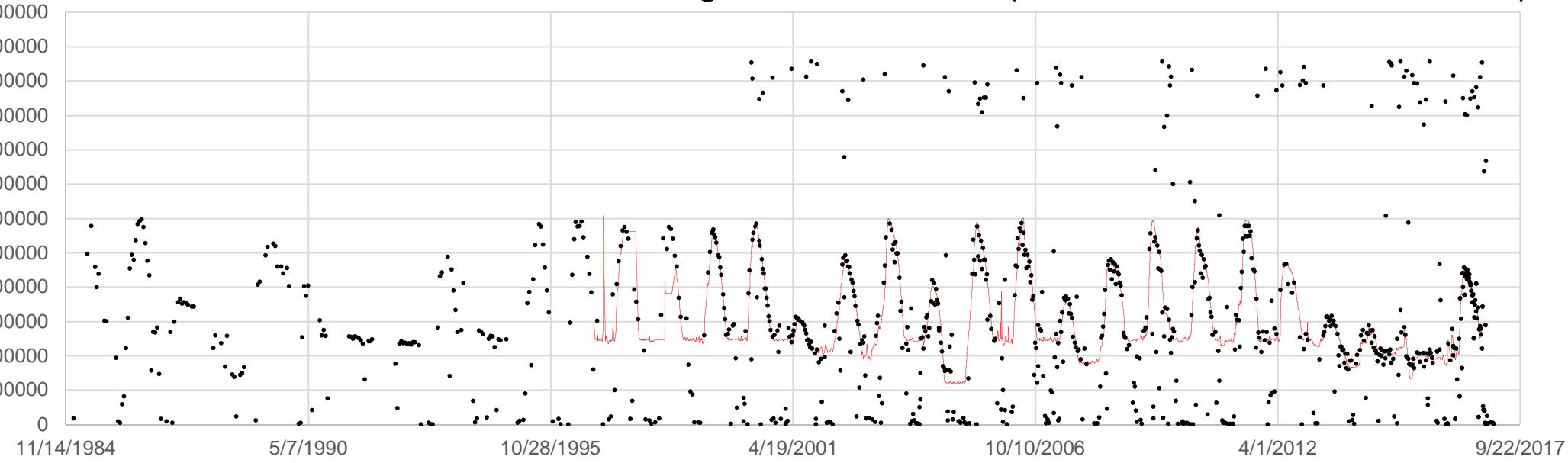
http://bit.ly/global_reservoirs_map_2016

http://bit.ly/agu16_reservoirs

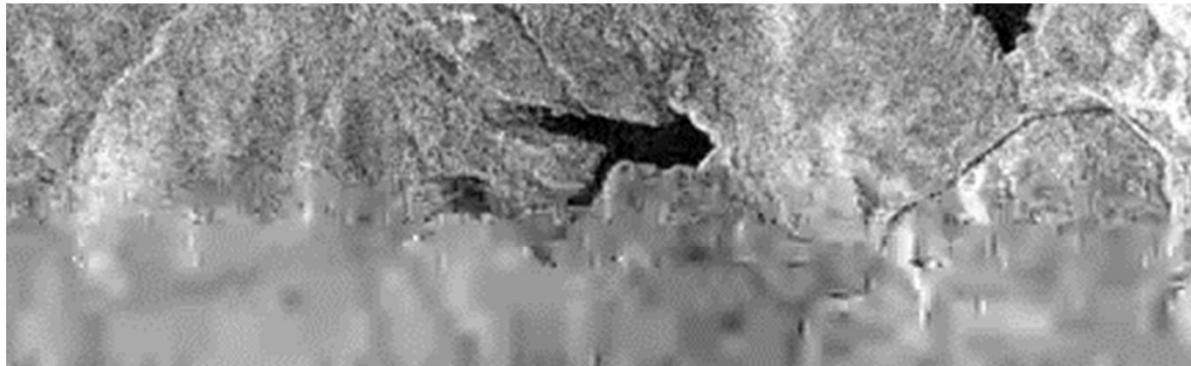
Surface water area estimated from satellite and from local water level station



Surface water area estimates using naive methods (no cloud/snow and NDWI=0)



0. Input images from multiple sensors



~1200 images, <30m

1. Detect water for cloud-free images

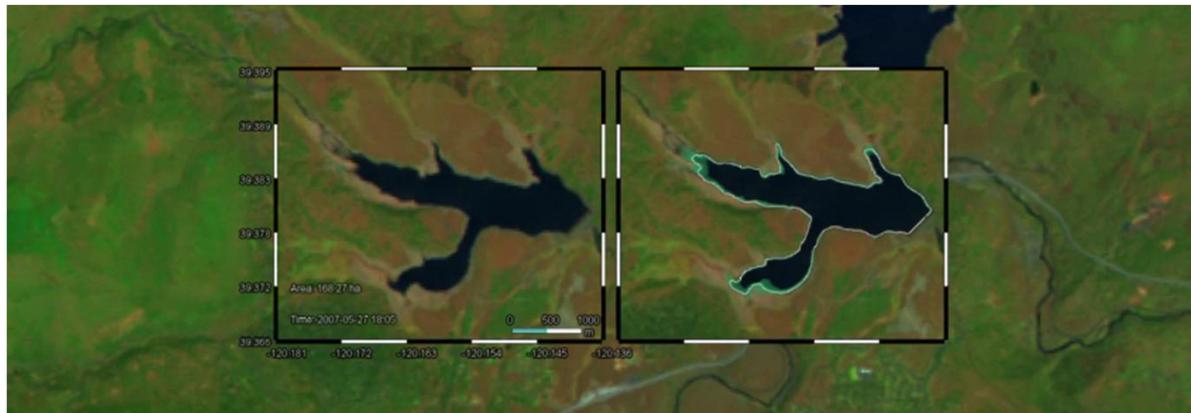


2. Estimate probability density (prior)

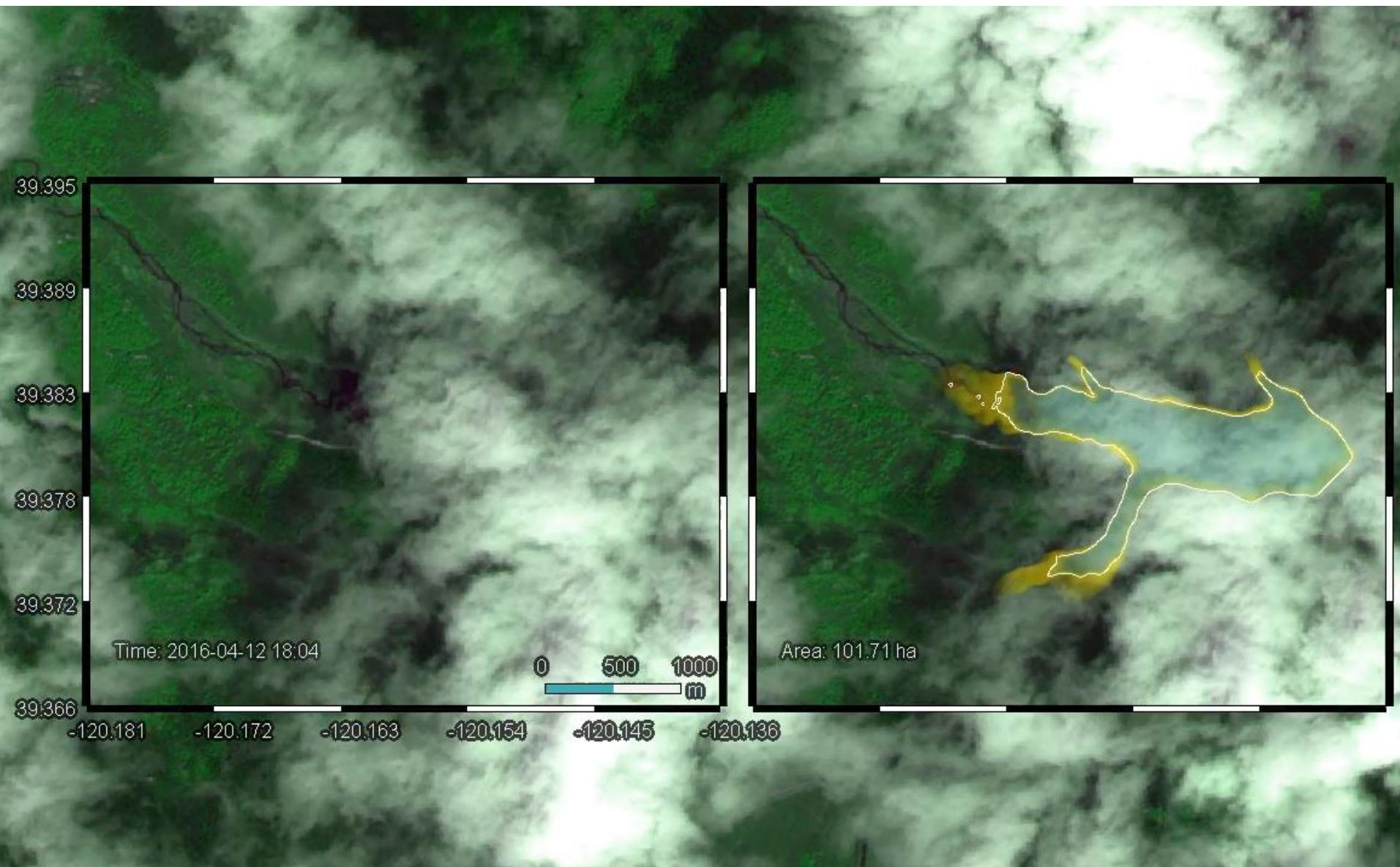


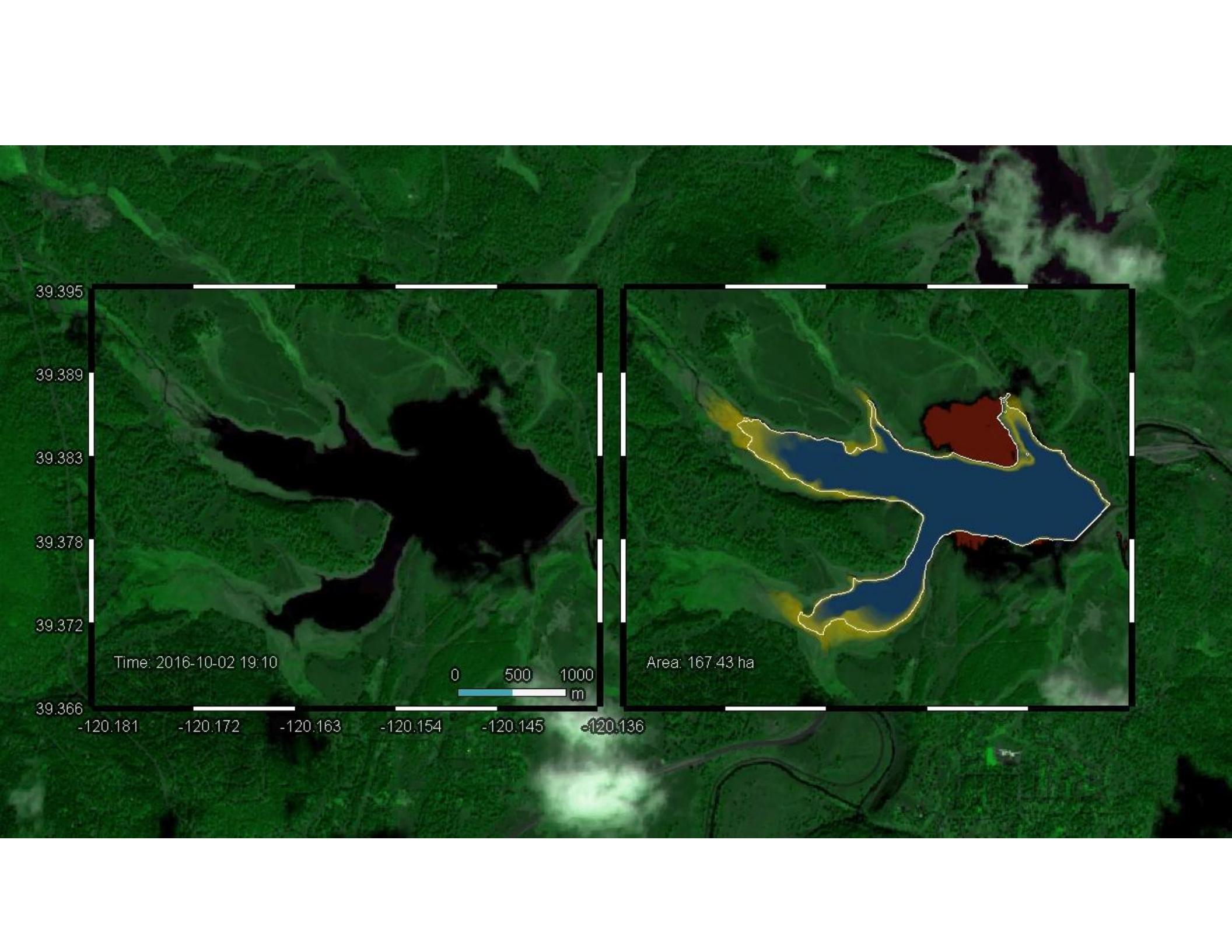
$$P(\text{water} | x, y, \text{cloud}=0)$$

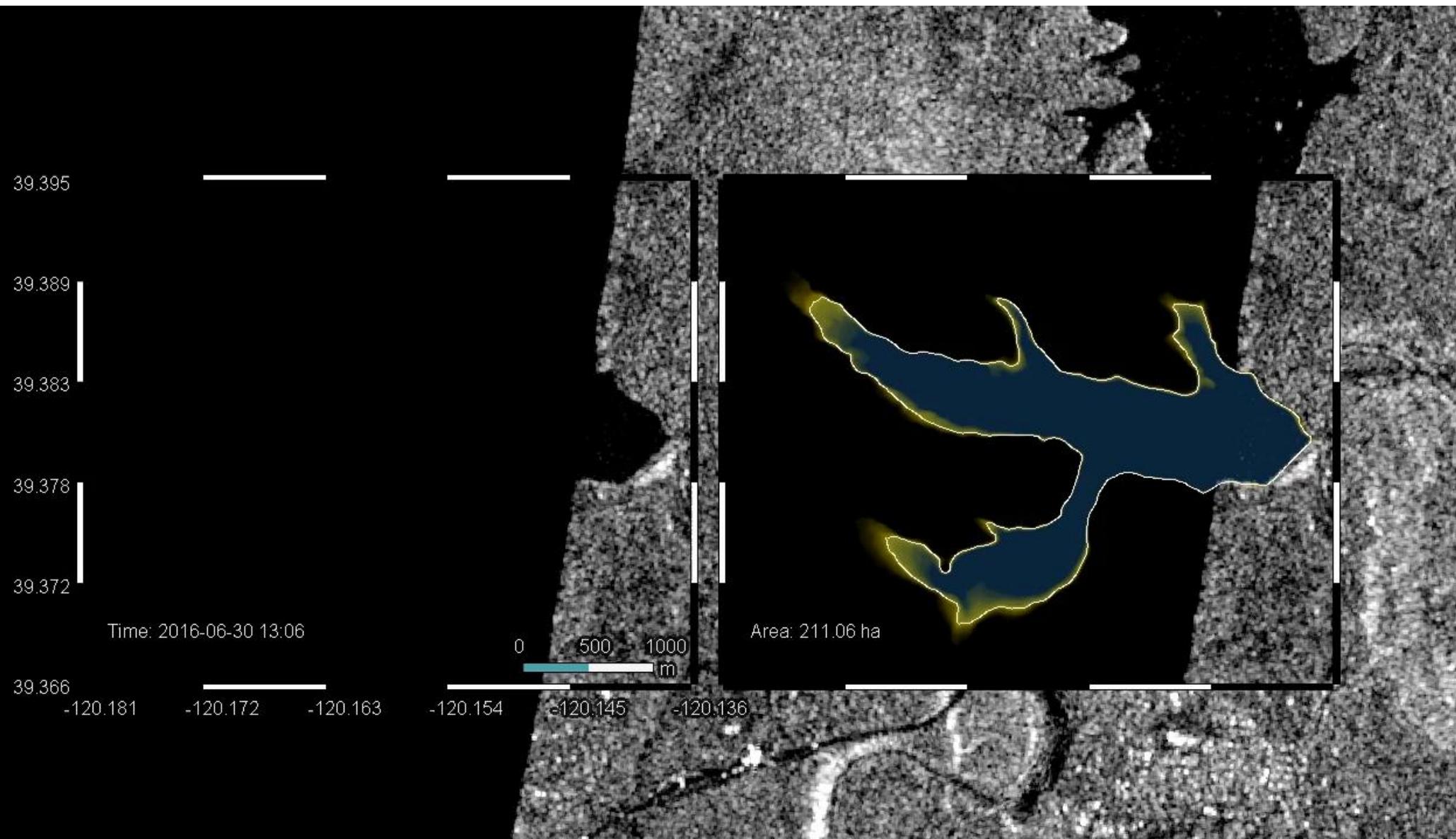
3. Estimate surface area using generative-discriminative algorithm



$$P(W|W^t) = \frac{P(W|W^t) \cdot P(W)}{P(W^t)}$$

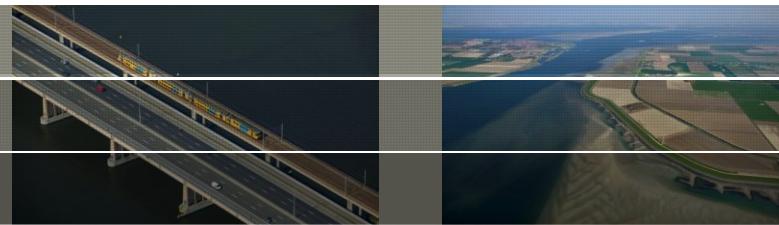








Exercices



Join Group: <https://groups.google.com/forum/#groupsettings/jerico-next-summerschool-2017>

Scripts repository: https://code.earthengine.google.com/?accept_repo=h2020-jerico-training

Slides: <http://bit.ly/jerico-next-gee-slides> ~120Mb

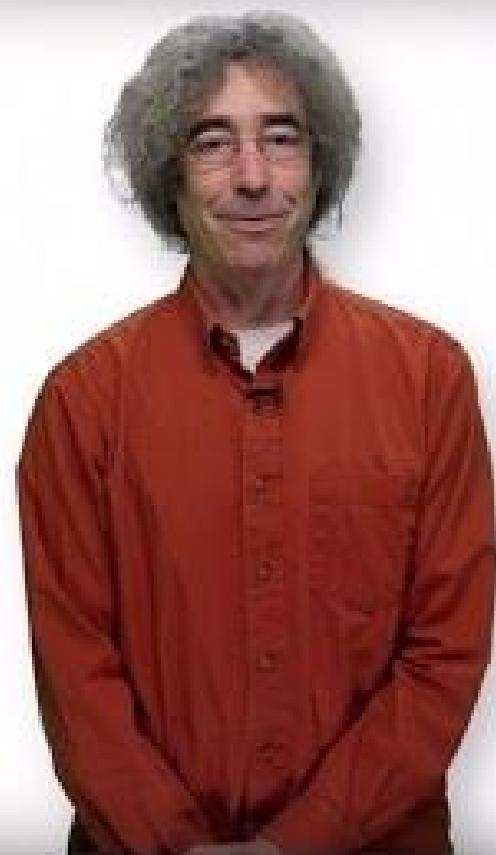
The screenshot shows the Google Earth Engine interface. At the top, there is a search bar labeled "Search places and datasets...". Below the search bar, there is a navigation bar with tabs: "Scripts" (which is selected), "Docs", and "Assets". A blue header bar contains the text "h2020-jerico-training". Underneath this, there is a list of 13 scripts, each represented by a small icon and a file name:

- 01 Hello World 1.js
- 02 Hello Image.js
- 03 Add Image to Map.js
- 04 Load and Filter Image Collections.js
- 05 Image Bands.js
- 06 Reducing Image Collections.js
- 07 Compute NDWI.js
- 08 Water Detection Otsu.js
- 09 Map a Function over an Image Collection.js
- 10 Linear Fit, Lights.js
- 11 Linear Fit, Water.js
- 12 Percentile Composite.js
- 13 AHN.js

At the bottom of the script list, there are three small icons: a gear, a pencil, and a trash can. To the right of the script list, there is a vertical sidebar with a "1" icon and a small "i" icon. At the very bottom of the sidebar, there are three more icons: a gear, a pencil, and a trash can.

Google Earth Engine

Introduction to planetary-scale geospatial analysis



Get an Image



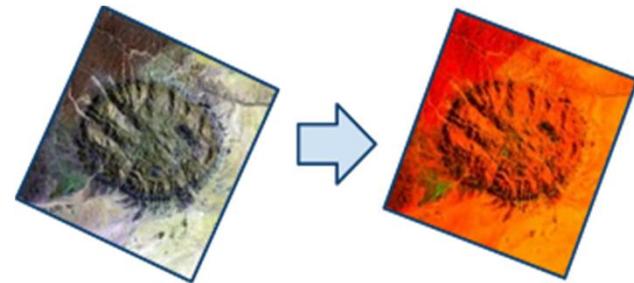
Pick your: projection, resolution, bands, bounding-box, visualization
Access as: Web map, KML, GeoTIFF

Global-scale Algorithm Processing

Google

Get an Image

Apply an algorithm to an image



Library functions or script your own.

Global-scale Algorithm Processing

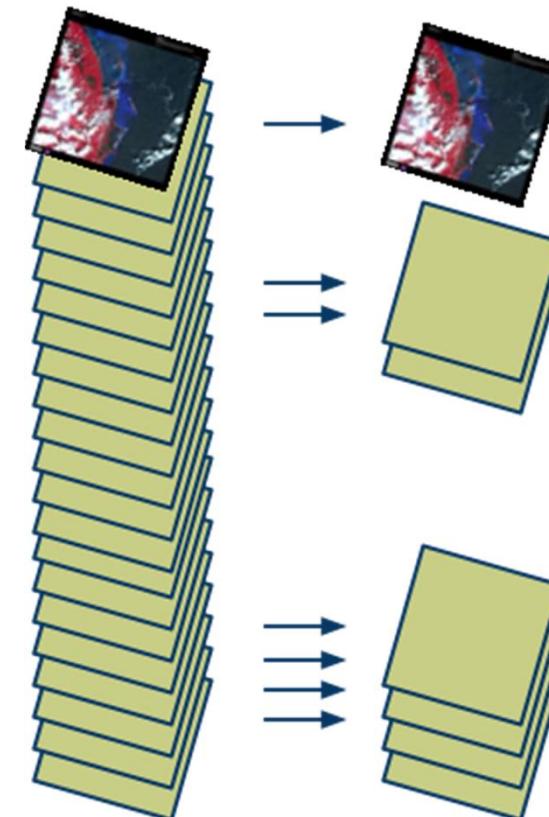
Google

Get an Image

Apply an algorithm to an image

Filter a collection

Time, Space & Metadata search



Global-scale Algorithm Processing

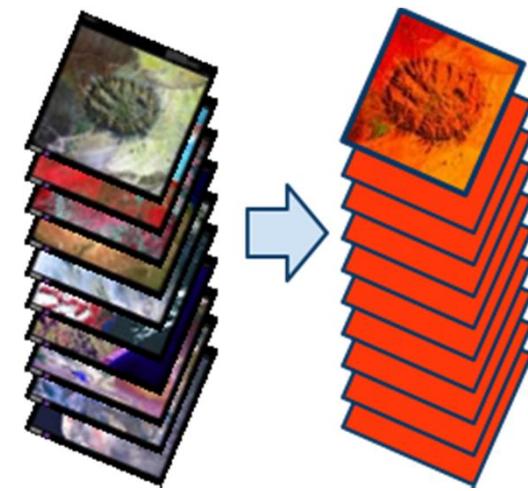


Get an Image

Apply an algorithm to an image

Filter a collection

Map an algorithm over a collection



$N \rightarrow N$

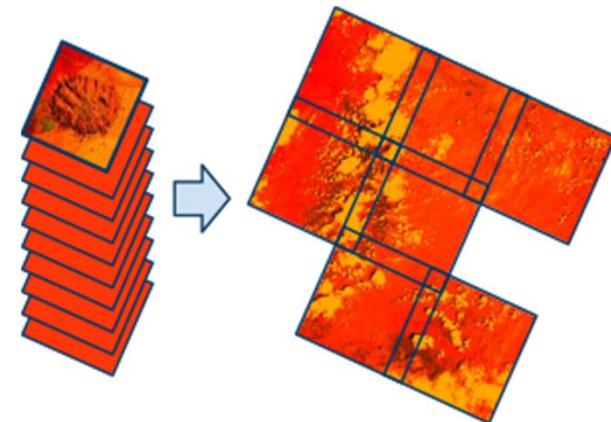
Get an Image

Apply an algorithm to an image

Filter a collection

Map an algorithm over a collection

Reduce a collection



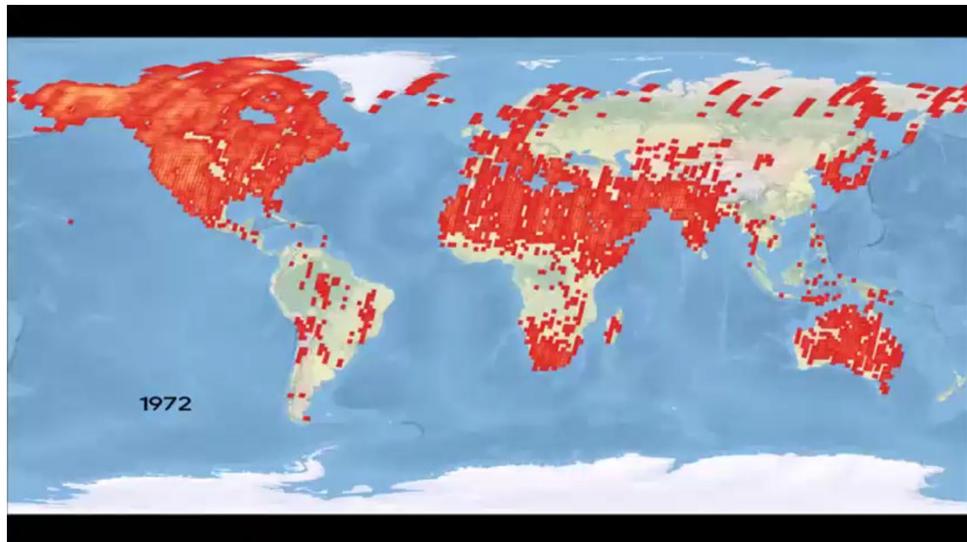
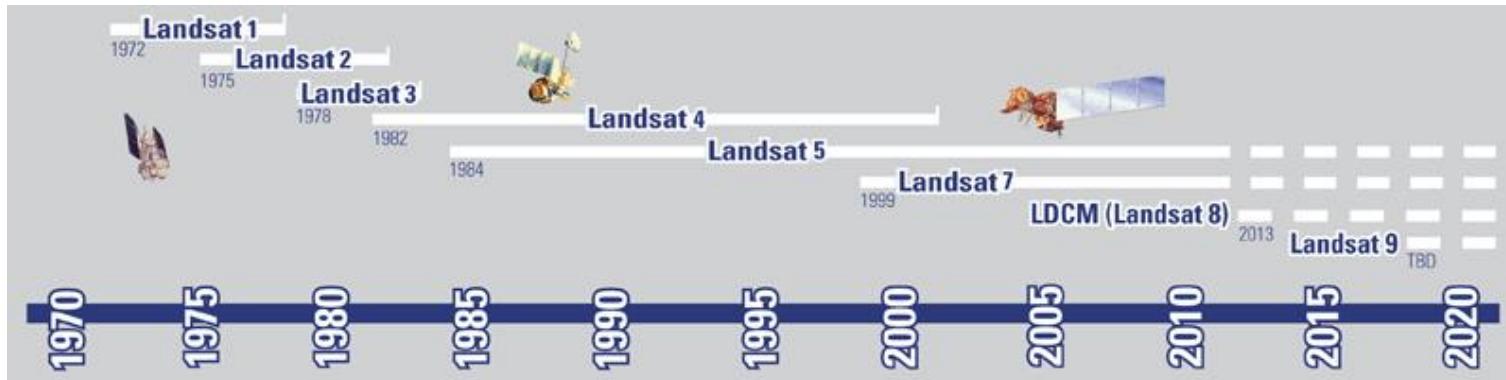
$N \rightarrow 1$ or $N \rightarrow M$



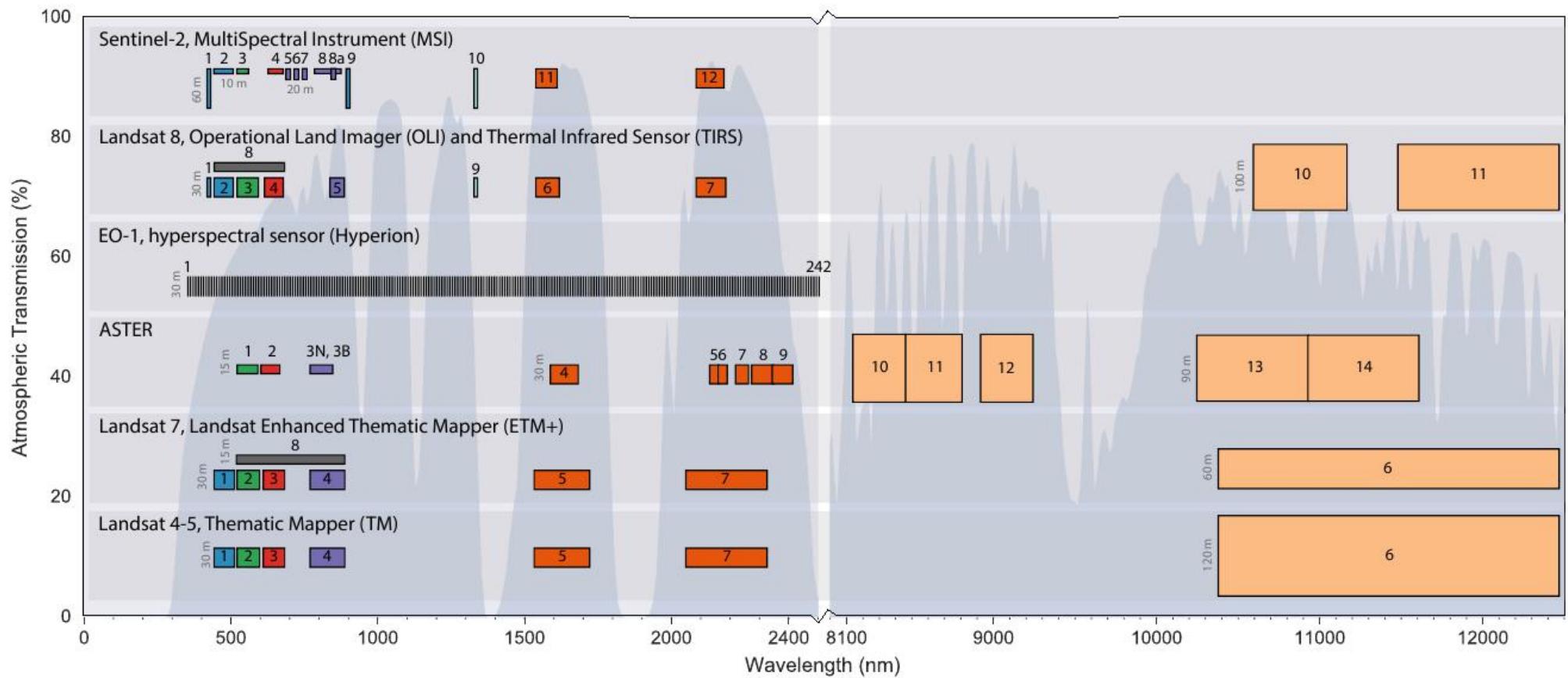
Optical Satellite Image Analysis



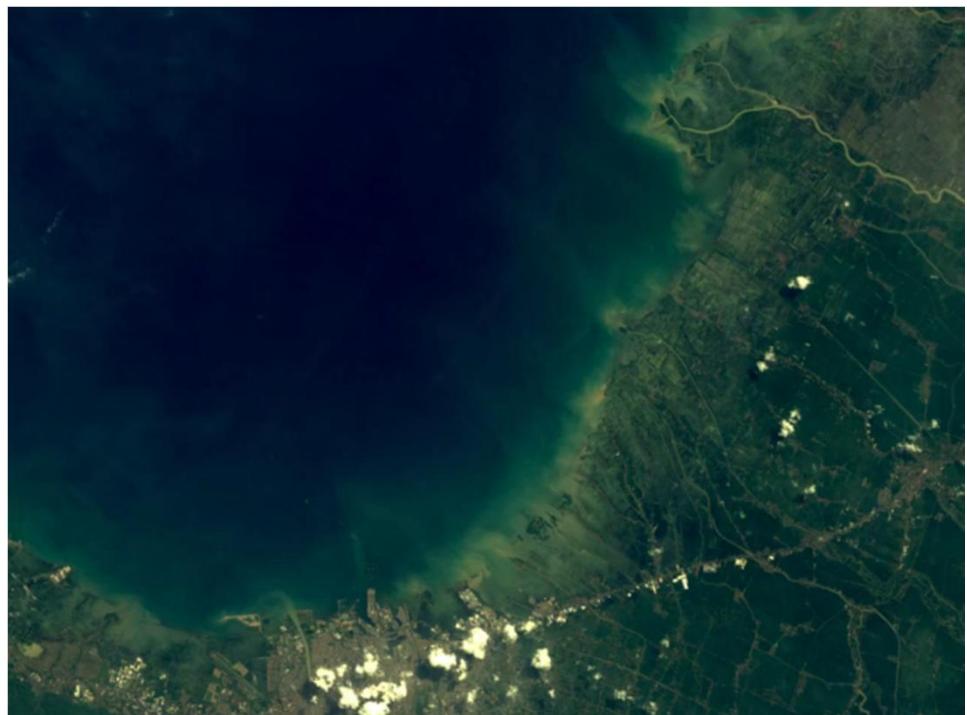
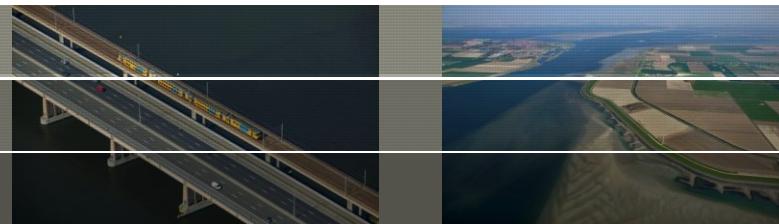
LANDSAT mission



https://youtu.be/YP0et8I_bvY - true/false color composites
https://youtu.be/YP0et8I_bvY - landsat orbits

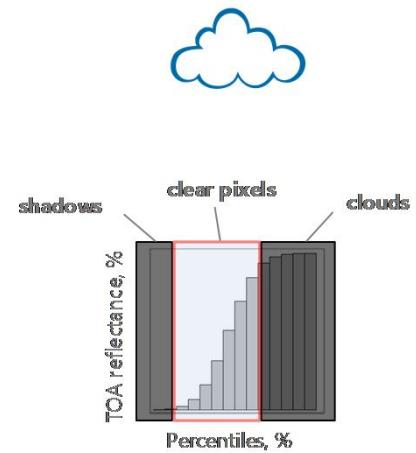
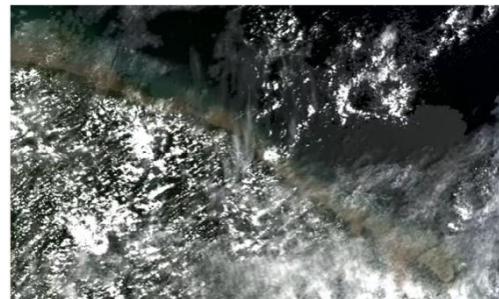
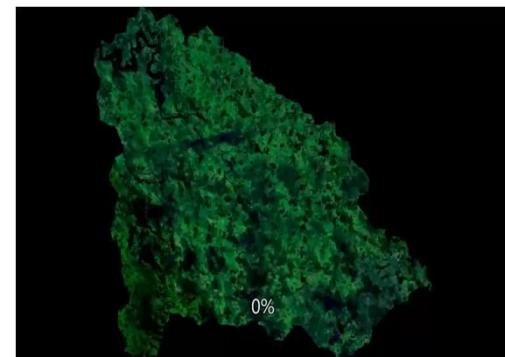


Visible and false color

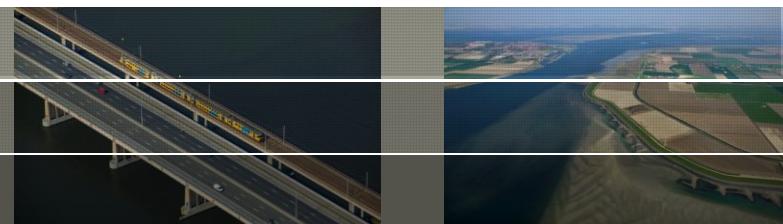


Deltares

The actual images vs. percentile composites



Deltares



EarthEnv

Global, remote-sensing supported environmental layers for assessing status and trends in biodiversity, ecosystems, and climate

HOME PUBLICATIONS PARTNERS PRESS TEAM

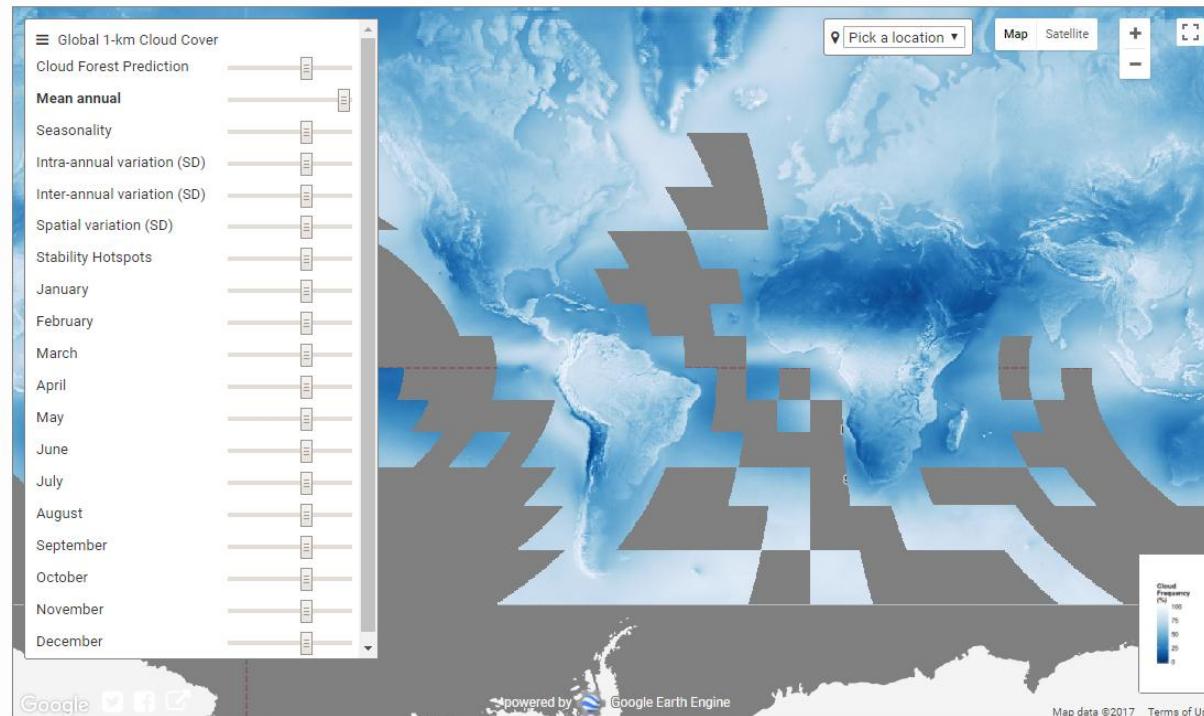
Global 1-km Cloud Cover

The datasets integrate 15 years of twice-daily remote sensing-derived cloud observations at 1-km resolution. For additional information about the integration approach and the evaluations of the datasets, please see the associated journal article:

Wilson AM, Jetz W (2016) Remotely Sensed High-Resolution Global Cloud Dynamics for Predicting Ecosystem and Biodiversity Distributions. *PLoS Biol* 14(3): e1002415. doi:10.1371/journal.pbio.1002415

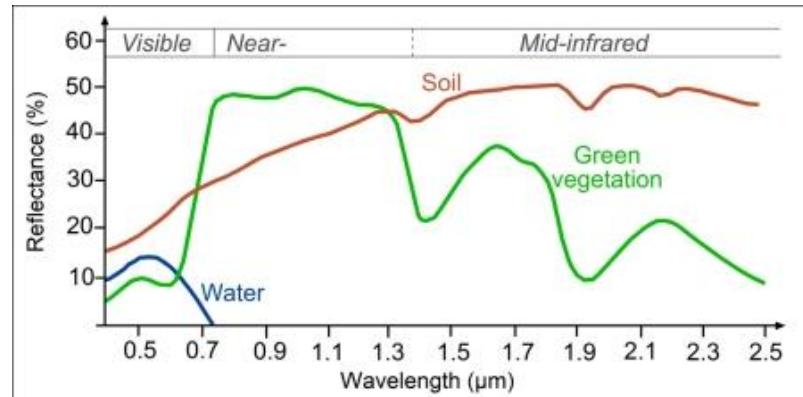
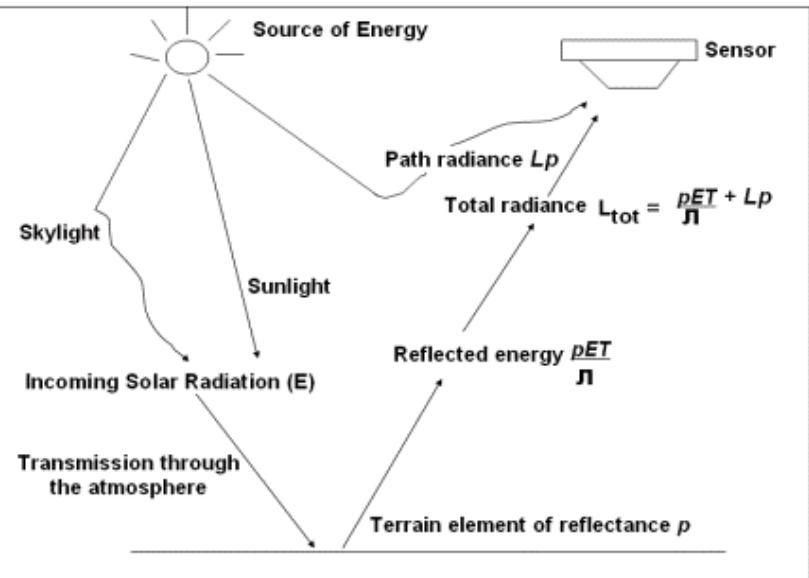
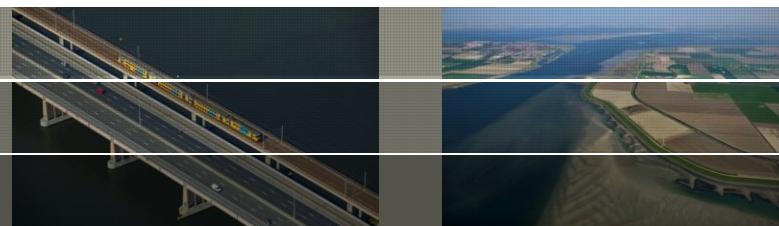
Dataset Details

Cloud cover can influence numerous important ecological processes including reproduction, growth, survival, and behavior, yet our assessment of its importance at the appropriate spatial scales has remained remarkably limited. If captured over large extent yet at sufficiently fine spatial grain cloud cover dynamics may provide key information for delineating a variety of habitat types and predicting species distributions. Here we develop new near-global, fine-grain ($\approx 1\text{km}$) monthly cloud frequencies from 15 years of twice-daily MODIS satellite images that expose spatio-temporal cloud cover dynamics of previously undocumented global complexity. We demonstrate that cloud cover varies strongly in its geographic heterogeneity and that the direct, observation-based nature of cloud-derived metrics can improve predictions of habitats, ecosystem, and species distributions with reduced spatial autocorrelation compared to commonly used



<http://www.earthenv.org/cloud>

Deltares



$$L_\lambda = \alpha_\lambda \times Q_\lambda + \beta_\lambda$$

$$\rho_\lambda = \frac{\pi \times L_\lambda \times d^2}{ESUN_\lambda \times \cos\theta_s}$$



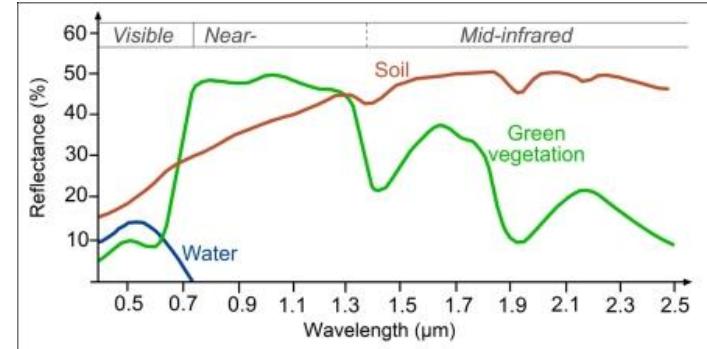
Cloud
Snow / ice
Topographic correction
Shadows (clouds, hills)



Spatial resolution
Temporal resolution
Spectral resolution
Radiometric resolution

Water detection

$$NDWI_{McFeeters} = \frac{\rho_{green} - \rho_{nir}}{\rho_{green} + \rho_{nir}}$$



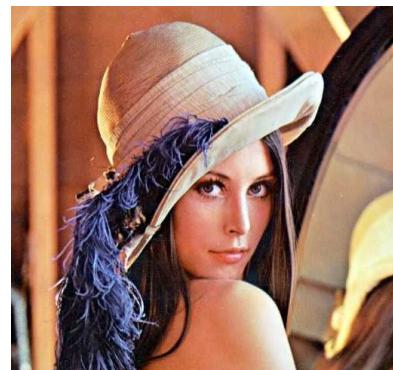
$$NDWI_{Xu} = \frac{\rho_{green} - \rho_{swirl}}{\rho_{green} + \rho_{swirl}}$$



Threshold?



Water detection



$$G = \sqrt{G_x^2 + G_y^2}$$

$$\Theta = \text{atan2}(G_y, G_x)$$

Canny Edge Detection

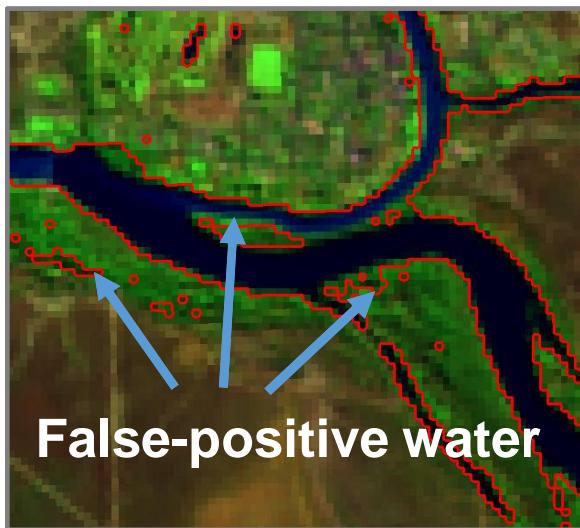


Otsu Thresholding

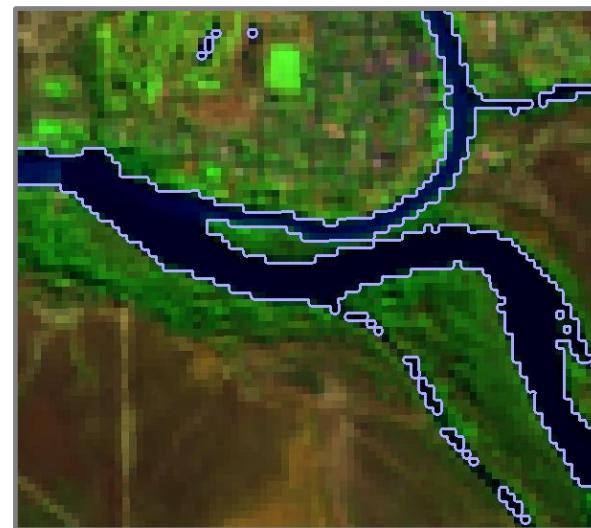


$$\sigma_w^2(t) = \omega_1(t)\sigma_1^2(t) + \omega_2(t)\sigma_2^2(t)$$

Water detection



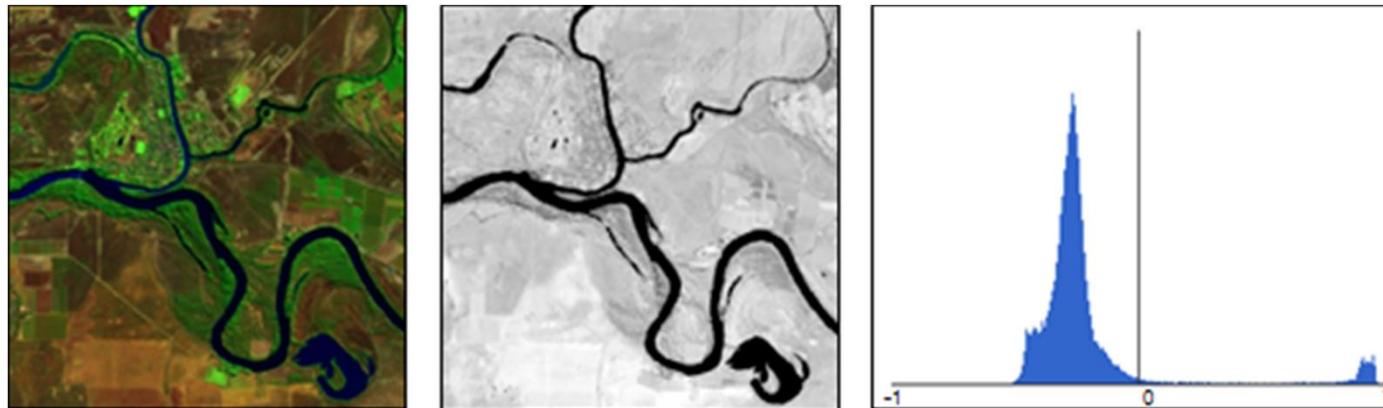
MNDWI=0



MNDWI=0.34

Water detection

Donchys et. al. 2016, <http://www.mdpi.com/2072-4292/8/5/386>



Compute Index → Detect Edges → Buffer → Compute Threshold → Threshold

$$I = \frac{\rho_{green} - \rho_{swir1}}{\rho_{green} + \rho_{swir1}}$$

$$C = \text{Canny}(I, \sigma, th)$$

$$I_c = \{I | I \in C \oplus S\}$$

$$T = \text{Otsu}(I_c)$$

$$\text{Water} = \{I | I < T\}$$



Source: <https://code.earthengine.google.com/65493c1cae67bb86c038e5bef3b4ab2d>

Python: https://github.com/gena/gena.github.io/blob/master/experiments/figure_water_detection.ipynb

Links

1. [Homepage](#) - official Google Earth Engine homepage
2. [Code Editor \(Playground\)](#) - main EE GUI (JavaScript)
3. [Developers Forum](#) - most EE discussions occur here
4. [Issue Tracker](#) - issue tracker
5. [Timelapse](#) - global timelapse video (Landsat)
6. [Private Git Sources](#) - browse your private EE git repositories
7. [Documentation](#) - Users Guide
8. [Earthengine Api](#)
9. [Selected Vector Datasets](#)
10. [Earth Engine resources for higher education](#)
11. [User Summit 2016](#)
12. [gsutil tool](#)
13. [Google Cloud Storage Documentation](#)

Selected Scripts



Multisensor Chart

S1 ascending / descending

S1 speckle filters

OSM & SRTM

SLIC unsupervised classification

LoG sharpening

Regular Grid

Elevation Profile

PCA

$$\frac{\partial I}{\partial t} = \frac{\partial^2 (c \cdot I)}{\partial x \partial y}$$

$$c = \frac{1}{1 + (G/K)^2}$$

